

Timed Automata

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Visited concepts of **syntax** and **semantics**

Explored a simple concurrent language (CCS) and its semantics

Analysed central ideas of **concurrency** and **synchronisation**

We will now see how **time** fits in the items above

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The very basics of timed automata

Parallel Composition

Semantics

Saying that an airbag in a car crash **eventually inflates** is insufficient – it would be better to say that

in a car crash the airbag inflates **within 20ms**

*Correctness in time-critical systems not only depends on the logical result of the computation, but also **on the time at which the results are produced***

[Baier & Katoen, 2008]

Examples of time-critical systems

Network-based traffic lights

Lights activate at specific time intervals

Bounded retransmission protocol

Communication of large files between a remote unit and a video/audio equipment. Correctness relies on

- transmission and synchronisation delays
- time-out values

Many others

pacemakers, autonomous driving, electric grids . . .

This chapter

We will explore an **automaton-based formalism** with an explicit notion of **clock**

Timed Automata [Alur & Dill, 90]

Emphasis on the **reachability** problem for showing (in)correctness

Associated tool

- UPPAAL [Behrmann, David, Larsen, 04]

UPPAAL = (Uppsala University + Aalborg University) [1995]

- A toolbox for modelling and analysis of timed systems
- Systems modelled as **networks** of timed automata enriched with **integer variables** and **channel synchronisations**
- Properties specified in a subset of CTL



Computation Tree Logic

<https://uppaal.org/>

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Motivation

The very basics of timed automata

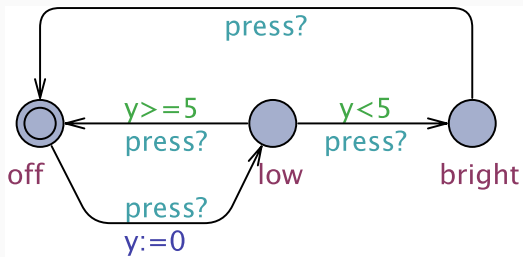
Parallel Composition

Semantics

Finite-state machines equipped with **real-valued clocks**

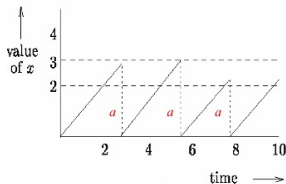
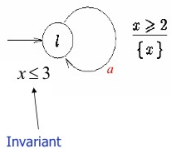
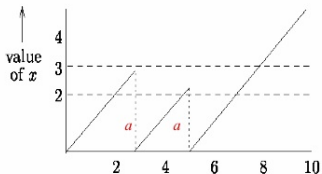
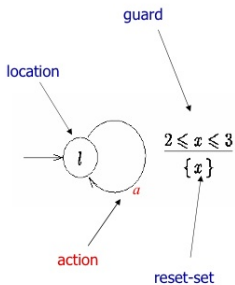
- clocks can only be read or
- reset to zero (after which they start increasing their value again as time progresses)
- a clock's value corresponds to time elapsed since its last reset
- all clocks proceed synchronously (i.e. at the same rate)

Example: the lamp interrupt



(extracted from UPPAAL)

Guards, updates, and invariants



Timed Automata

A timed automaton is a tuple $\langle \mathbf{L}, \mathbf{L}_0, \mathbf{Act}, \mathbf{C}, \mathbf{Tr}, \mathbf{Inv} \rangle$

- \mathbf{L} a set of locations and $\mathbf{L}_0 \subseteq \mathbf{L}$ set of **initial** locations
- \mathbf{Act} set of actions (**channels**) and \mathbf{C} set of clocks
- $\mathbf{Tr} \subseteq \mathbf{L} \times \mathcal{C}(\mathbf{C}) \times \mathbf{Act} \times \mathcal{P}(\mathbf{C}) \times \mathbf{L}$ is a **transition** relation

$$l_1 \xrightarrow{g, a, U} l_2$$

transition from location l_1 to l_2 , labelled by a , enabled if **guard** g holds; when performed resets the set U of clocks

- $\mathbf{Inv} : \mathbf{L} \rightarrow \mathcal{C}(\mathbf{C})$ assignment of invariants to locations

$\mathcal{C}(\mathbf{C})$ denotes the set of clock constraints over a set \mathbf{C} of clocks

Clock constraints

Each constraint is formed according to

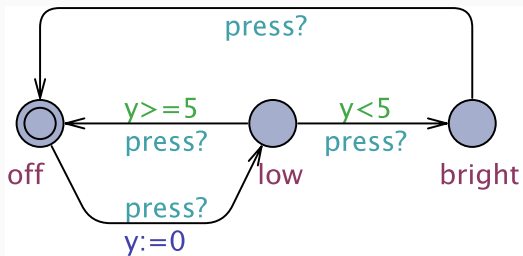
$$g ::= x \square n \mid x - y \square n \mid g \wedge g \mid \text{true}$$

where $x, y \in C$, $n \in \mathbb{N}$ and $\square \in \{<, \leq, >, \geq, =\}$

This is used in

- transitions (enabling conditions) – a transition cannot occur if its guard is false
- locations (safety conditions) – a location must be left before its invariant becomes false

A revisit of the lamp interrupt



Exercise: define $\langle L, L_0, Act, C, Tr, Inv \rangle$

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Action labels as channels

Communication mechanism analogous to CCS

Shared clocks

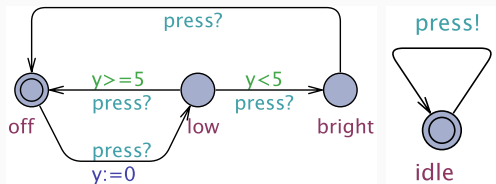
Definition

Let $H = Act_1 \cap Act_2$. The parallel composition of ta_1 and ta_2 synchronising on H is the timed automaton

$$ta_1 \parallel_H ta_2 := \langle L_1 \times L_2, L_{0,1} \times L_{0,2}, \mathbf{Act}, C_1 \cup C_2, \mathbf{Tr}, \mathbf{Inv} \rangle$$

- $\mathbf{Act} = ((Act_1 \cup Act_2) - H) \cup \{\tau\}$
- $\mathbf{Inv}(l_1, l_2) = Inv_1(l_1) \wedge Inv_2(l_2)$
- \mathbf{Tr} is given by:
 - $(l_1, l_2) \xrightarrow{g, a, U} (l'_1, l_2)$ if $a \notin H \wedge l_1 \xrightarrow{g, a, U} l'_1$
 - $(l_1, l_2) \xrightarrow{g, a, U} (l_1, l'_2)$ if $a \notin H \wedge l_2 \xrightarrow{g, a, U} l'_2$
 - $(l_1, l_2) \xrightarrow{g, \tau, U} (l'_1, l'_2)$ if $a \in H \wedge l_1 \xrightarrow{g_1, a, U_1} l'_1 \wedge l_2 \xrightarrow{g_2, \bar{a}, U_2} l'_2$
with $g = g_1 \wedge g_2$ and $U = U_1 \cup U_2$

Example: (re)visiting the lamp interrupt



In Uppaal

- Complementary actions marked by `?` and `!` annotations)
- All channels in H are **private**

Exercise: worker, hammer, nail

Write down the parallel composition of the following automata

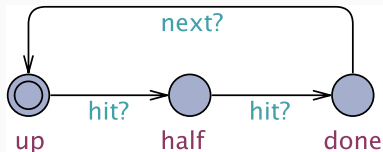
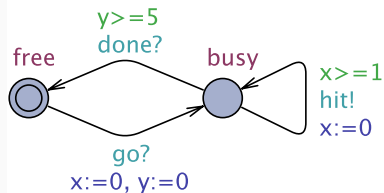
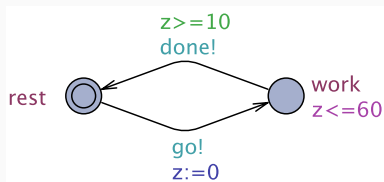


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Semantics of timed automata

Syntax	Semantics
<i>How to write</i>	<i>How to execute</i>
CCS	LTS
Timed Automaton	TLTS (Timed LTS)

Timed LTS

Introduce **delay transitions** to capture the passage of time

$s \xrightarrow{a} s'$ for $a \in Act$, are ordinary transitions due to action occurrence

$s \xrightarrow{d} s'$ for $d \in \mathbb{R}_{\geq 0}$, are **delay** transitions

subject to sanity constraints ...

1. Time additivity

$$(s \xrightarrow{d} s' \wedge 0 \leq d' \leq d) \Rightarrow s \xrightarrow{d'} s'' \xrightarrow{d-d'} s' \text{ for some state } s''$$

2. Delay transitions are deterministic

$$(s \xrightarrow{d} s' \wedge s \xrightarrow{d} s'') \Rightarrow s' = s''$$

Every TA ta defines a TLTS

$$\mathcal{T}(ta)$$

whose states are pairs

$\langle \text{location, clocks valuations} \rangle$

Clock valuation

Definition

A clock valuation η for a set of clocks C is a function

$$\eta : C \longrightarrow \mathbb{R}_{\geq 0}$$

assigning to each clock $x \in C$ its current value ηx

Satisfaction of Clock Constraints

$$\eta \models x \square n \Leftrightarrow \eta x \square n$$

$$\eta \models x - y \square n \Leftrightarrow (\eta x - \eta y) \square n$$

$$\eta \models g_1 \wedge g_2 \Leftrightarrow \eta \models g_1 \wedge \eta \models g_2$$

Operations on clock valuations

Delay

For each $d \in \mathbb{R}_{\geq 0}$, valuation $\eta + d$ is given by

$$(\eta + d)x = \eta x + d$$

Reset

For each $R \subseteq C$, valuation $\eta[R]$ is given by

$$\begin{cases} \eta[R]x = \eta x & \text{if } x \notin R \\ \eta[R]x = 0 & \text{if } x \in R \end{cases}$$

From ta to $\mathcal{T}(ta)$

Let $ta = \langle L, L_0, Act, C, Tr, Inv \rangle$

$$\mathcal{T}(ta) = \langle \mathbf{S}, \mathbf{S}_0 \subseteq S, \mathbf{N}, \mathbf{T} \rangle$$

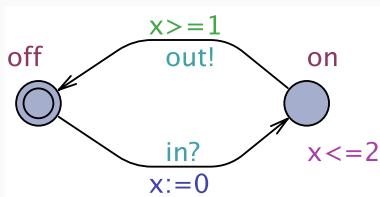
where

- $\mathbf{S} = \{(l, \eta) \in L \times (\mathbb{R}_{\geq 0})^C \mid \eta \models Inv(l)\}$
- $\mathbf{S}_0 = \{(\ell_0, \eta) \mid \ell_0 \in L_0 \wedge \eta x = 0 \text{ for all } x \in C\}$
- $\mathbf{N} = Act + \mathbb{R}_{\geq 0}$ (i.e., transitions can be labelled by actions or delays)
- $\mathbf{T} \subseteq S \times N \times S$ is given by

$$(l, \eta) \xrightarrow{a} (l', \eta') \quad \text{if} \quad \exists_{l' \xrightarrow{g, a, U} l' \in Tr} \eta \models g \wedge \eta' = \eta[U] \wedge \eta' \models Inv(l')$$

$$(l, \eta) \xrightarrow{d} (l, \eta + d) \quad \text{if} \quad \eta + d \models Inv(l)$$

Example: the simple switch pt. 1

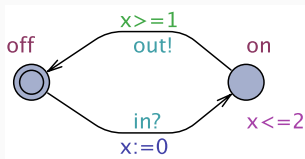


\mathcal{T} (Simple switch)

$$S = \{(off, t) \mid t \in \mathbb{R}_{\geq 0}\} \cup \{(on, t) \mid 0 \leq t \leq 2\}$$

where t is a shorthand for η such that $\eta x = t$

Example: the simple switch pt. II



\mathcal{T} (Simple switch)

$$(off, t) \xrightarrow{d} (off, t + d) \text{ for all } t, d \geq 0$$

$$(off, t) \xrightarrow{in?} (on, 0) \text{ for all } t \geq 0$$

$$(on, t) \xrightarrow{d} (on, t + d) \text{ for all } t, d \geq 0 \text{ and } t + d \leq 2$$

$$(on, t) \xrightarrow{out!} (off, t) \text{ for all } 1 \leq t \leq 2$$