Structural design with Alloy

Alcino Cunha

lucid, systematic, and penetrating treatment of basic and dynamic data structures, sorting, recursive algorithms, language structures, and compiling

NIKLAUS WIRTH

Algorithms +
Data
Structures =
Programs

PRENTICE-HALL SERIES IN AUTOMATIC COMPUTATION

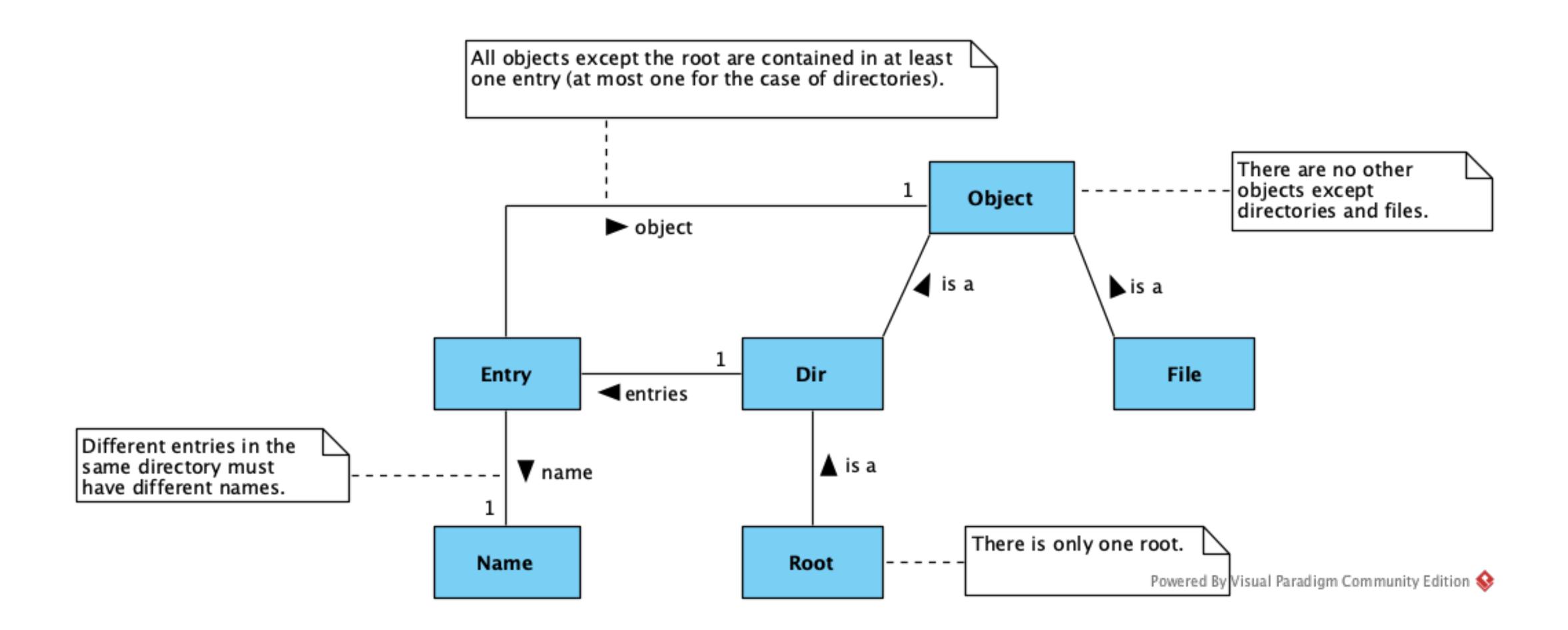
Software structures

- Architectures
- Database schemas
- Network topologies
- Ontologies
- Domain models

Structural design

- Understand entities and their relationships
- Elicit requirements
- Explore design alternatives

Domain modelling a la UML

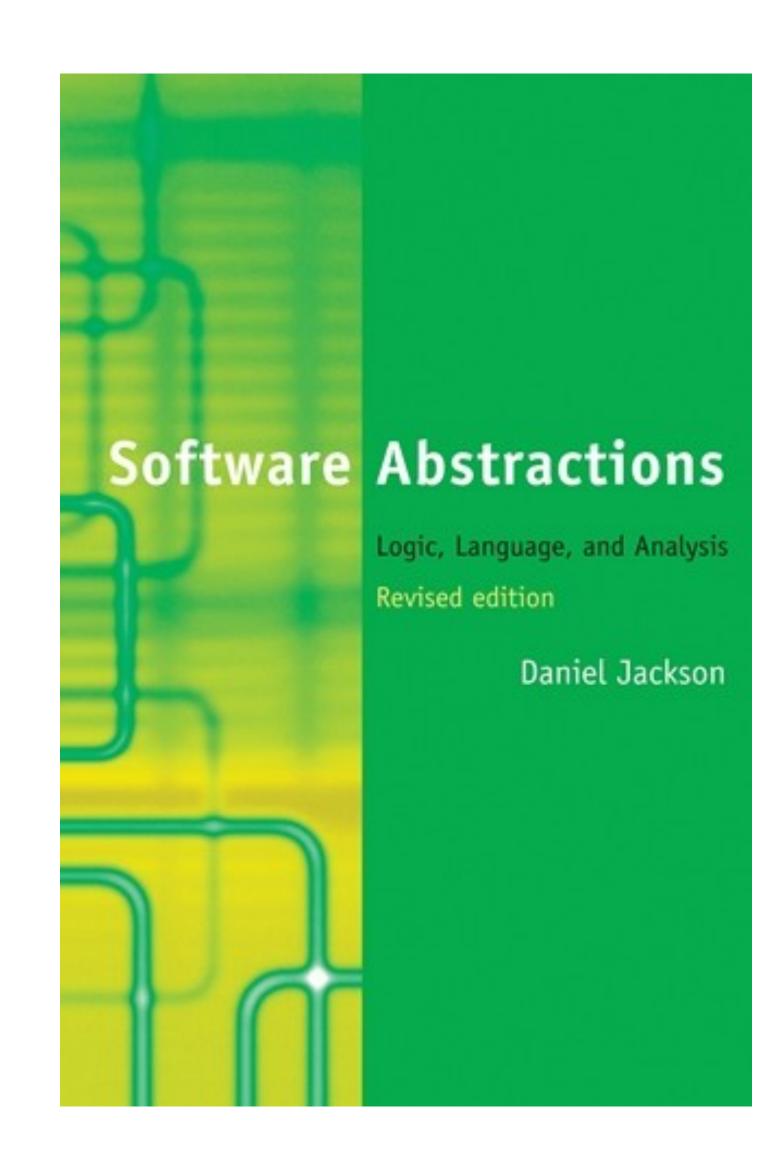


Domain modelling a la UML

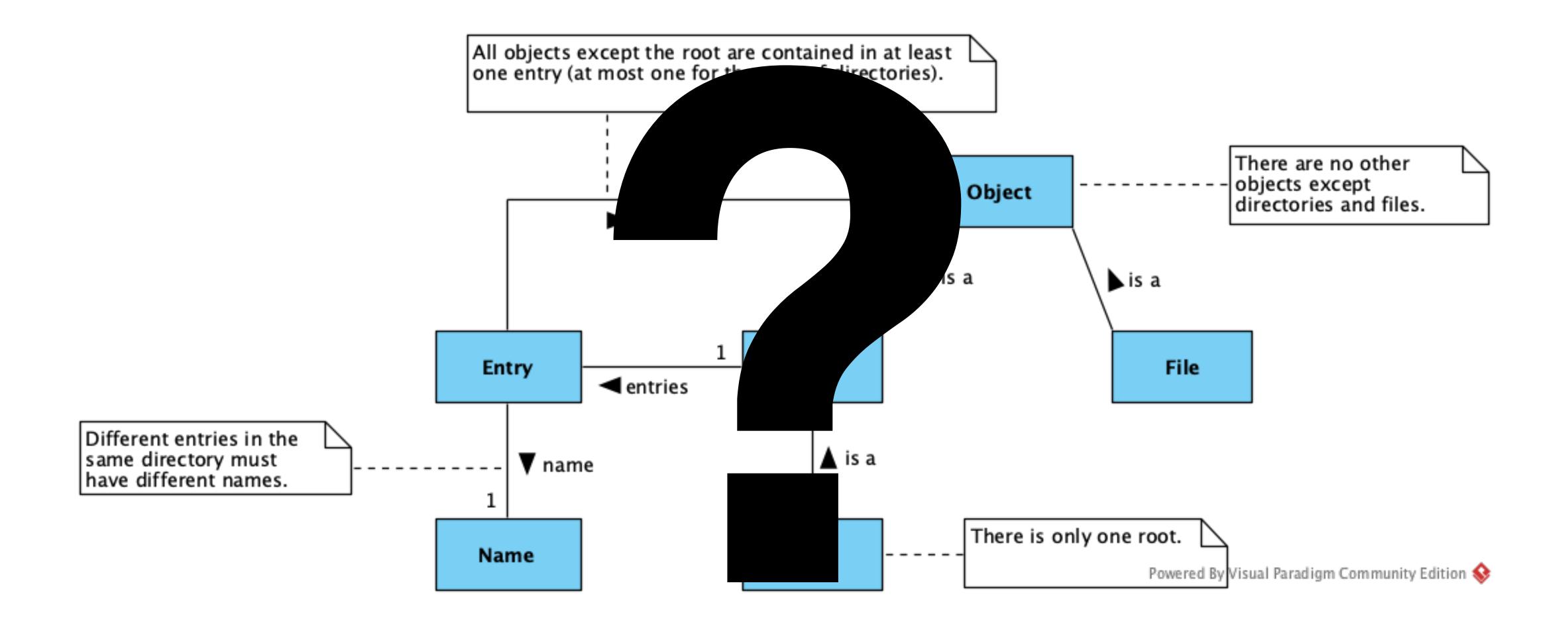
- How to validate the model?
- Any forgotten or redundant constraints?
- What exactly mean the constraints?
- Do the constraints entail all the expected properties?

Software design with Alloy

- Alloy is a formal modelling language
- Can be used to declare structures and events and specify constraints
- Models can be automatically analysed



Domain modelling with Alloy



Signatures and fields

Entities = Signatures

```
sig Object {}
sig Entry {}
sig Name {}
```

"Is a" = Extension

```
sig Dir extends Object {}
sig File extends Object {}
sig Root extends Dir {}
```

Signatures

- Signatures are sets
- Inhabited by atoms from a finite universe of discourse
- Top-level signatures are disjoint
- An extension signature is a subset of the parent signature
- Sibling extension signatures are disjoint

Relationships = Fields

```
sig Dir extends Object {
  entries : set Entry
}
sig Entry {
  object : set Object,
  name : set Name
}
```

Fields

- Fields are relations
- Inhabited by sets of tuples of atoms from the universe
- Fields are subsets of the Cartesian product of the source and target type signatures
- All tuples in a field have the same arity

Facts

• Facts specify assumptions

```
fact \{ \phi \}
```

Facts can be named

```
fact Name { φ }
```

A single fact can have several constraints, one per line

```
fact { R in A m \rightarrow m B }
```

Alloy	UML
set	0*
lone	01
some	1*
one	1

- In a multiplicity constraint the default multiplicity is set
- The target multiplicity can alternatively be specified in the declaration
- In field declarations the default target multiplicity is one

```
sig Dir extends Object {
 entries : set Entry
sig Entry {
 object : set Object,
 name : set Name
fact Multiplicities {
 entries in Dir one -> set Entry
 object in Entry set -> one Object
         in Entry set -> one Name
 name
```

```
sig Dir extends Object {
 entries : set Entry
sig Entry {
 object : one Object,
 name : one Name
fact {
 entries in Dir one -> set Entry
```

```
sig Dir extends Object {
 entries : set Entry
sig Entry {
 object: Object,
 name : Name
fact {
 entries in Dir one -> Entry
```

Bestiary

```
R in A set -> some B
                        // R is entire
R in A set -> lone B // R is simple
R in A some -> set B // R is surjective
R in A lone -> set B
                        // R is injective
R in A lone -> some B
                        // R is a representation
R in A some -> lone B
                        // R is an abstraction
                        // R is a function
R in A set -> one B
R in A lone -> one B
                        // R is an injection
                        // R is a surjection
R in A some -> one B
R in A one -> one B // R is a bijection
```

Analysis

Commands

- Alloy has two types of analysis commands:
 - run { φ } asks for an example that satisfies φ
 - check { φ } asks for a counter-example that refutes assertion φ
- Likewise facts, commands can be named and can have several constraints, one per line
- In the visualiser it possible to ask for more examples or counter-examples by pressing New

Instances

- Both examples and counter-examples are instances of the model
- An instance is a valuation to all the signatures and fields
- An instance must satisfy the declarations and all the facts
- In an instance "everything is a relation"
 - Signatures are unary relations (sets of unary tuples)
 - Constants are singleton unary relations (sets with a one unary tuple)

Scopes

- To ensure decidability commands have a scope
- The scope imposes a limit on the size of the (finite) universe the Analyzer will exhaustively explore
- The default scope imposes a limit of 3 atoms per top-level signature
- for can be used to specify a different scope for top-level signatures
- but can be used to specify different scopes for specific signatures

The small scope hypothesis

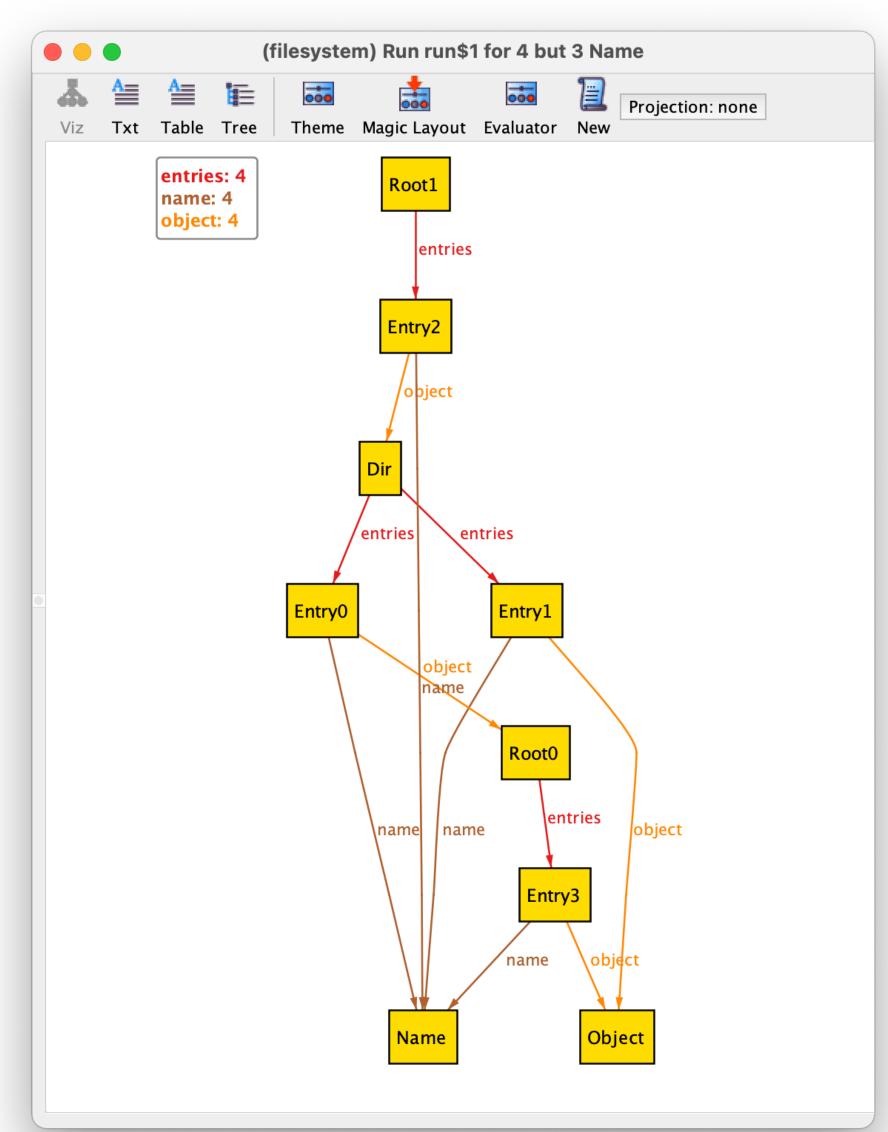
- If run { φ } returns an instance then φ is consistent, else φ MAY be inconsistent
 - Could be consistent with a bigger scope!
- If check $\{ \phi \}$ returns an instance then ϕ is invalid, else ϕ MAY be valid
 - Could be invalid with a bigger scope!!!
- Anecdotical evidence suggests that most invalid assertions (or consistent predicates) can be refuted (or witnessed) with a small scope

A simple command

```
run {} for 4 but 3 Name
```

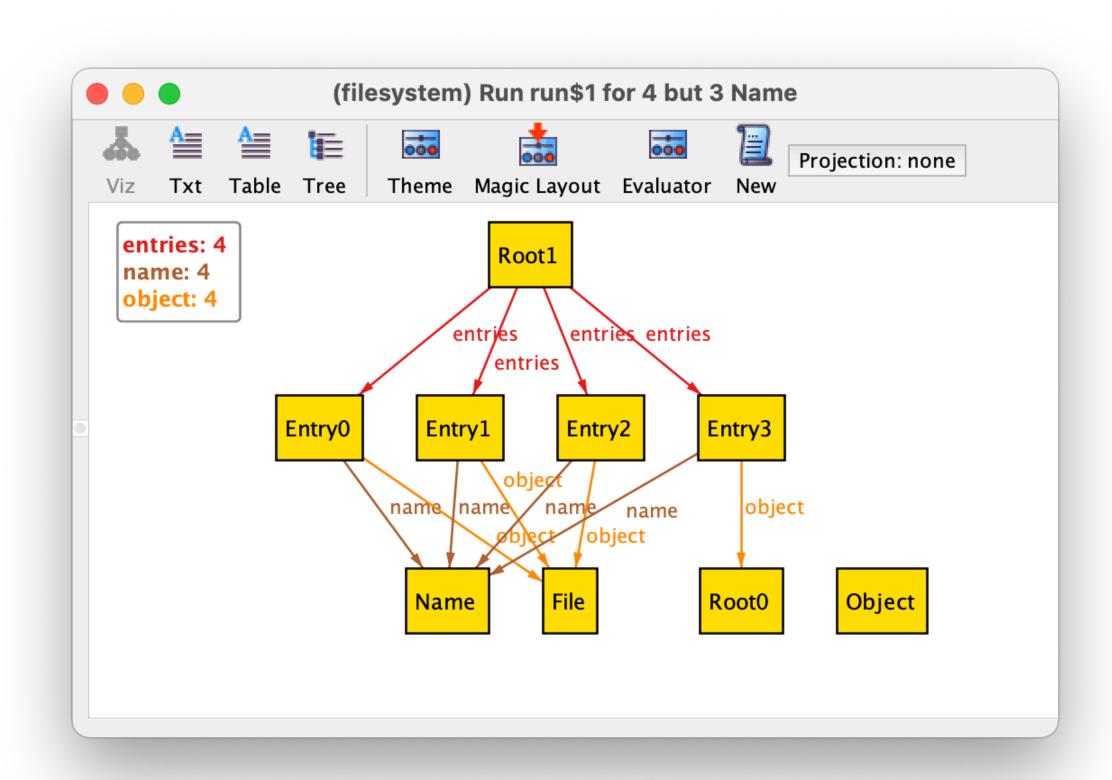
A simple command

run {} for 4 but 3 Name

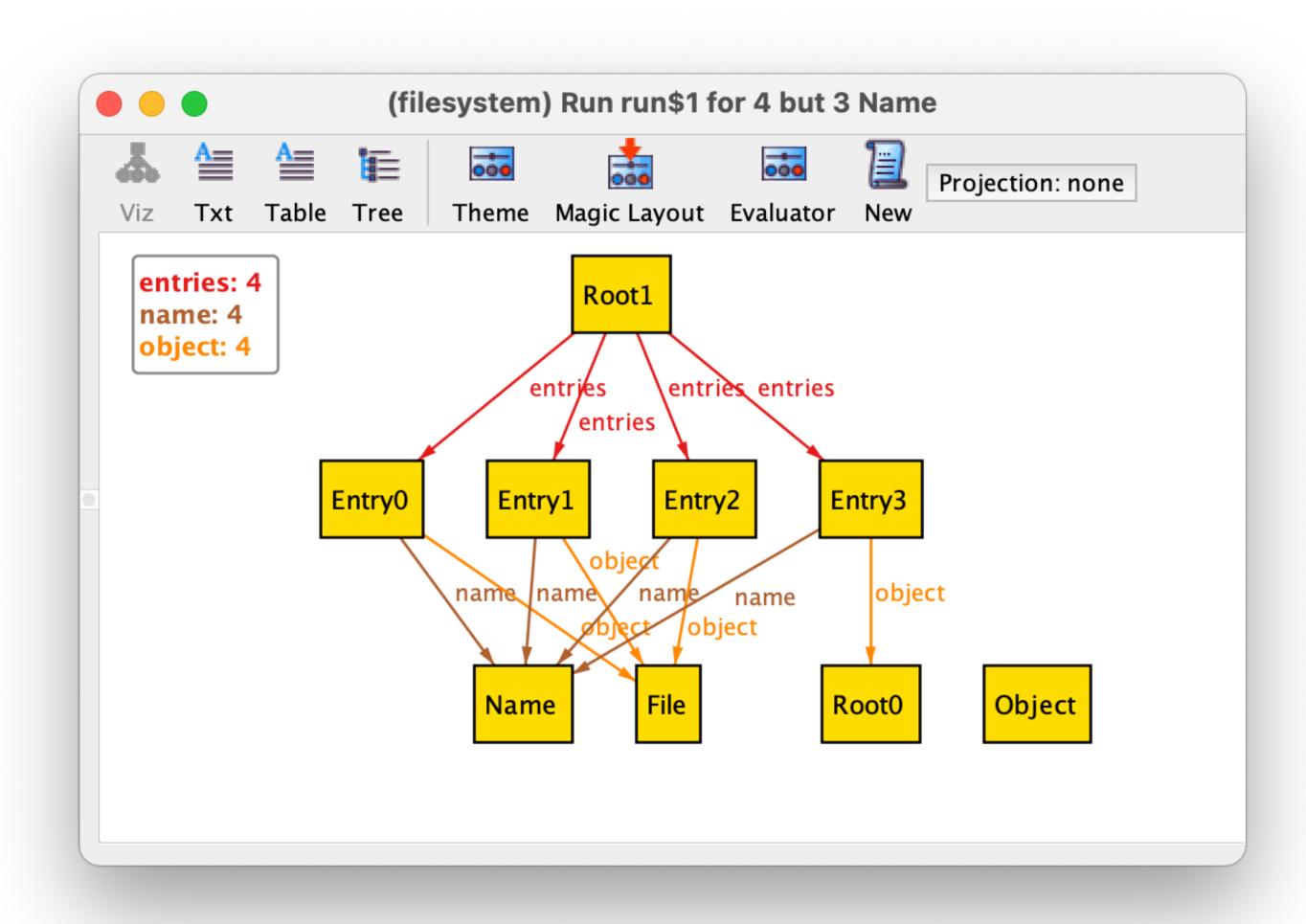


A simple command

run {} for 4 but 3 Name



Instances as graphs



Instances as sets

```
Object
        = {(Object),(Root0),(Root1),(File)}
Dir
        = {(Root0),(Root1)}
File = \{(File)\}
Root
        = {(Root0),(Root1)}
Entry
        = {(Entry0),(Entry1),(Entry2),(Entry3)}
Name
        = { (Name) }
entries = {(Root1,Entry1),(Root1,Entry2),(Root1,Entry3),(Root1,Entry0)}
        = {(Entry1, File), (Entry2, File), (Entry0, File), (Entry3, Root0)}
object
        = {(Entry0, Name), (Entry1, Name), (Entry2, Name), (Entry3, Name)}
name
```

Instances as tables

Object File Dir Entry Root Name Object File Root0 Root0 Entry0 Name File Entry1 Root1 Root1 Root0 Entry2 Root1 Entry3

entries	
Root1	Entry1
Root1	Entry2
Root1	Entry3
Root1	Entry0

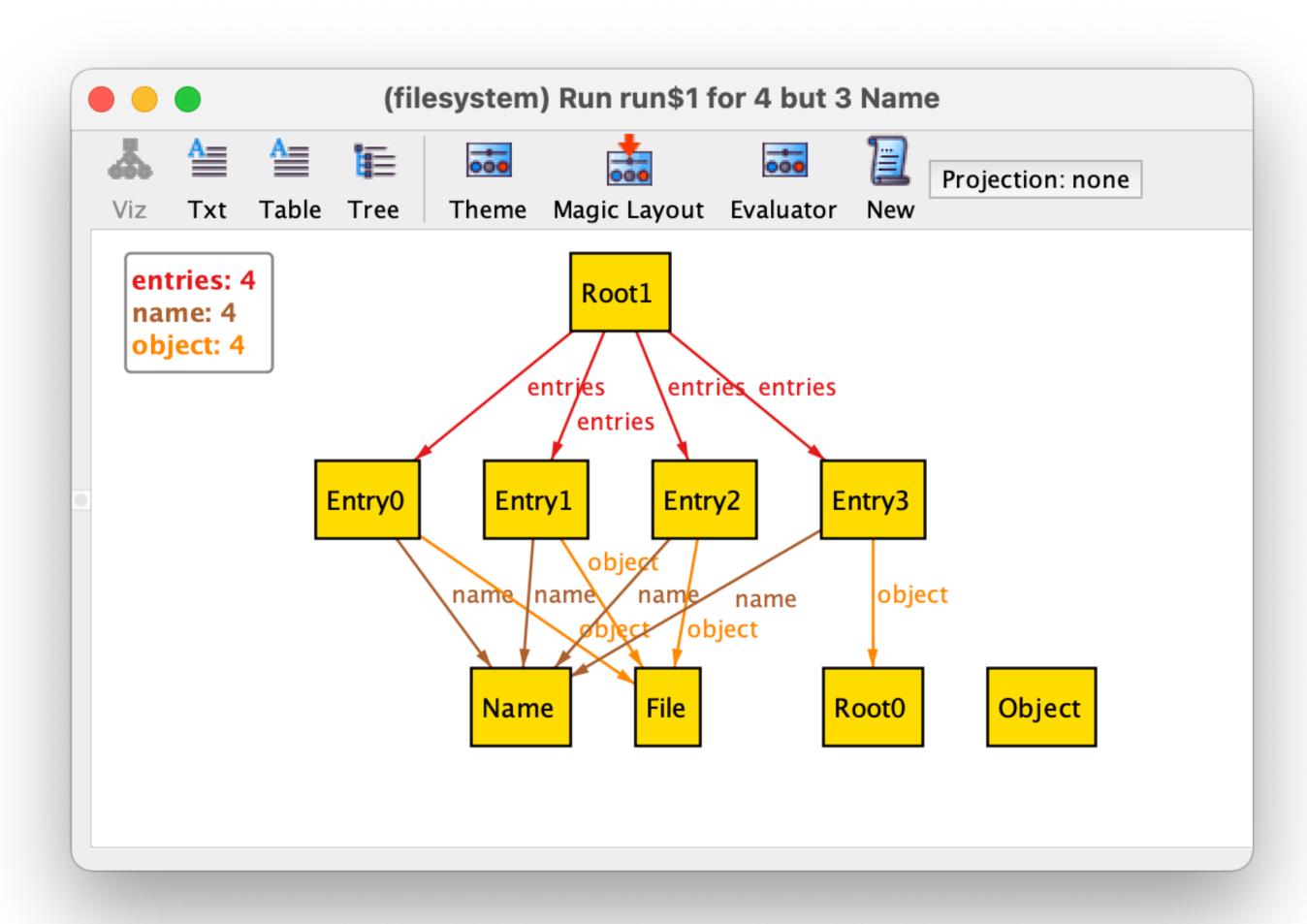
object		
Entry0	File	
Entry1	File	
Entry2	File	
Entry3	Root0	

name	
Entry0	Name
Entry1	Name
Entry2	Name
Entry3	Name

Atoms

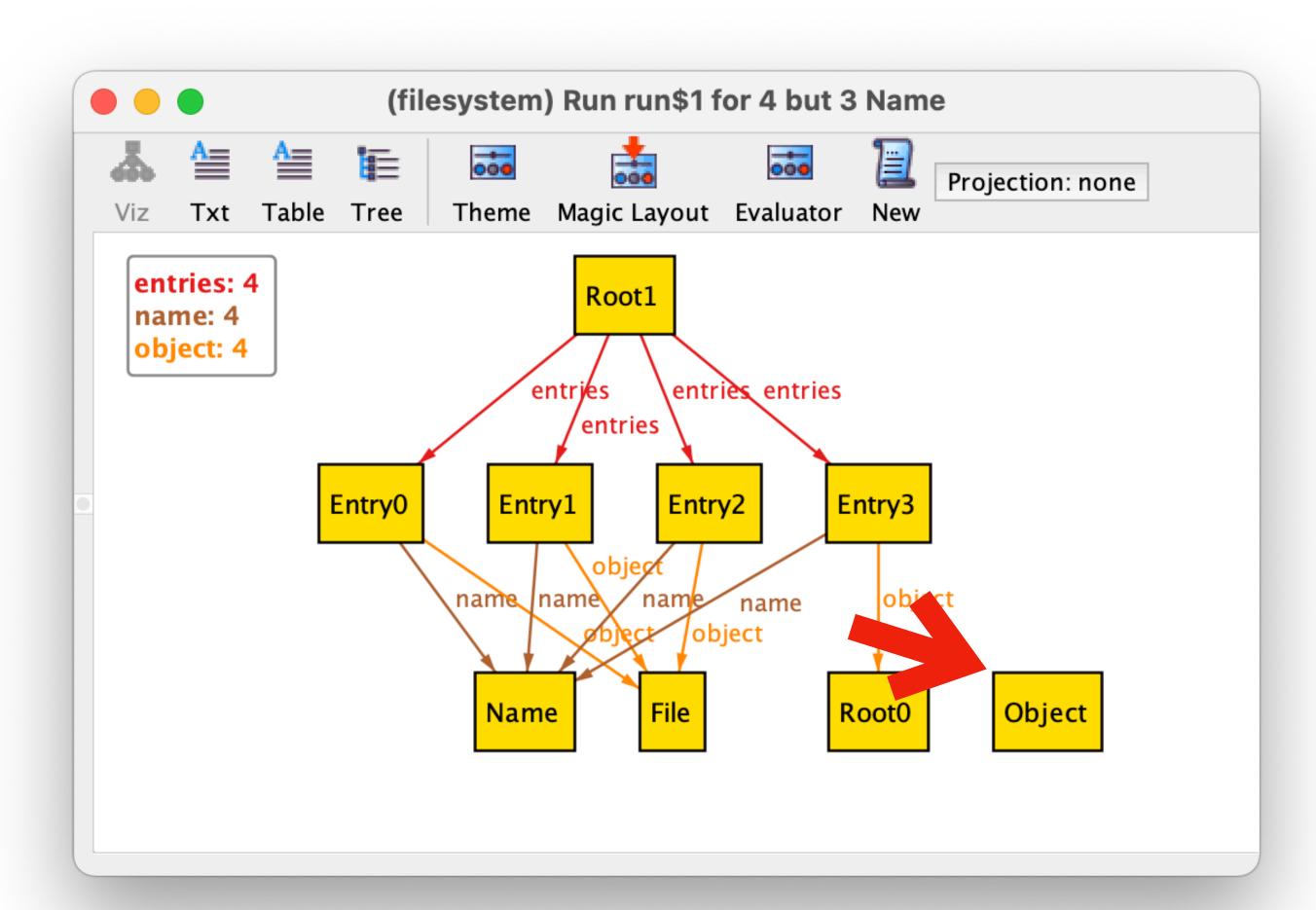
- The universe of discourse contains atoms
- Atoms are uninterpreted (no semantics)
- Named automatically according to the respective signatures
- Two instances are *isomorphic* (or *symmetric*) if they are equal modulo renaming
- The analysis implements a *symmetry breaking* mechanism to avoid returning isomorphic instances

The constraints



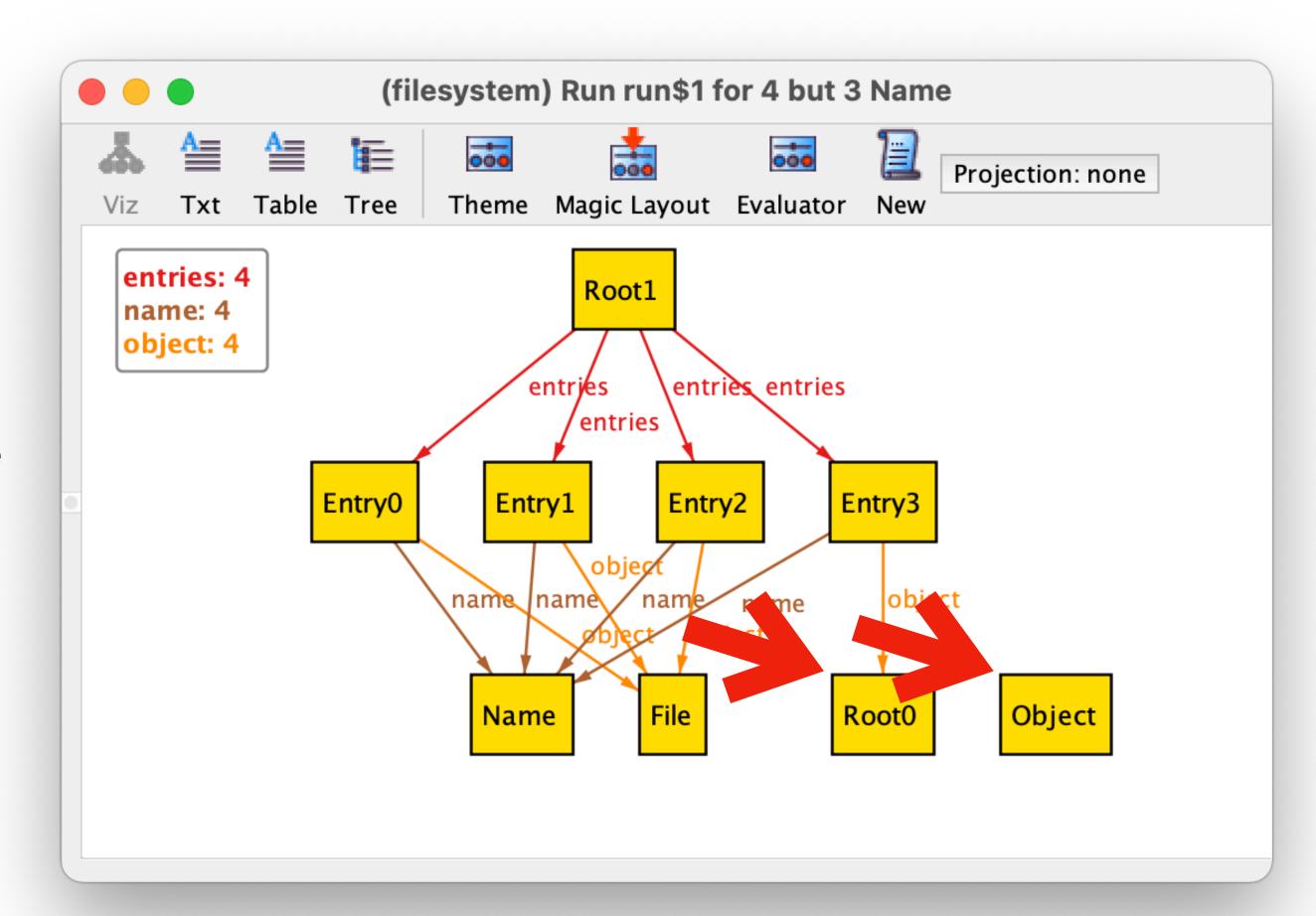
The constraints

 There are no other objects except directories and files



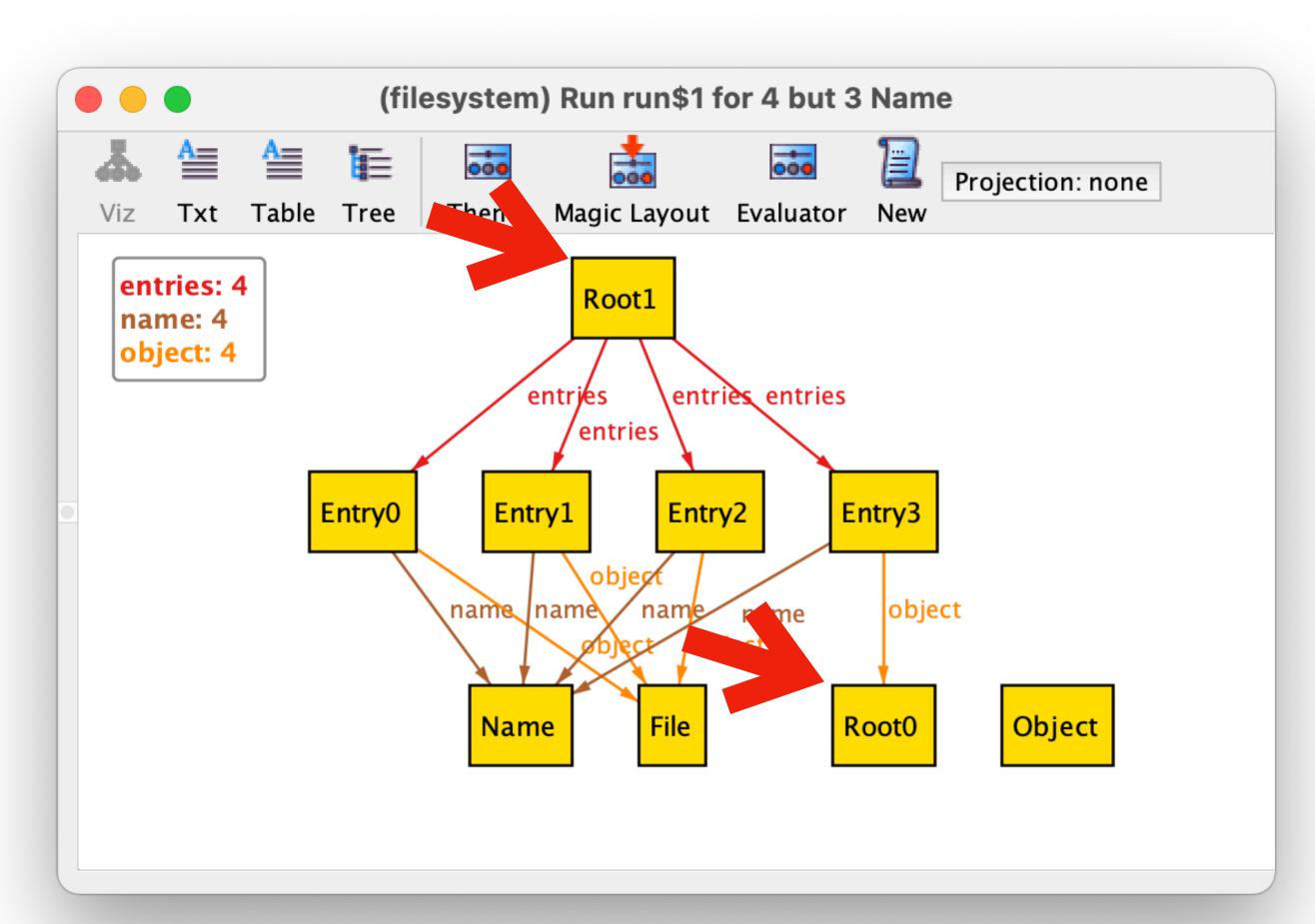
The constraints

- There are no other objects except directories and files
- All objects except the root are contained in at least one entry (at most one for the case of directories)



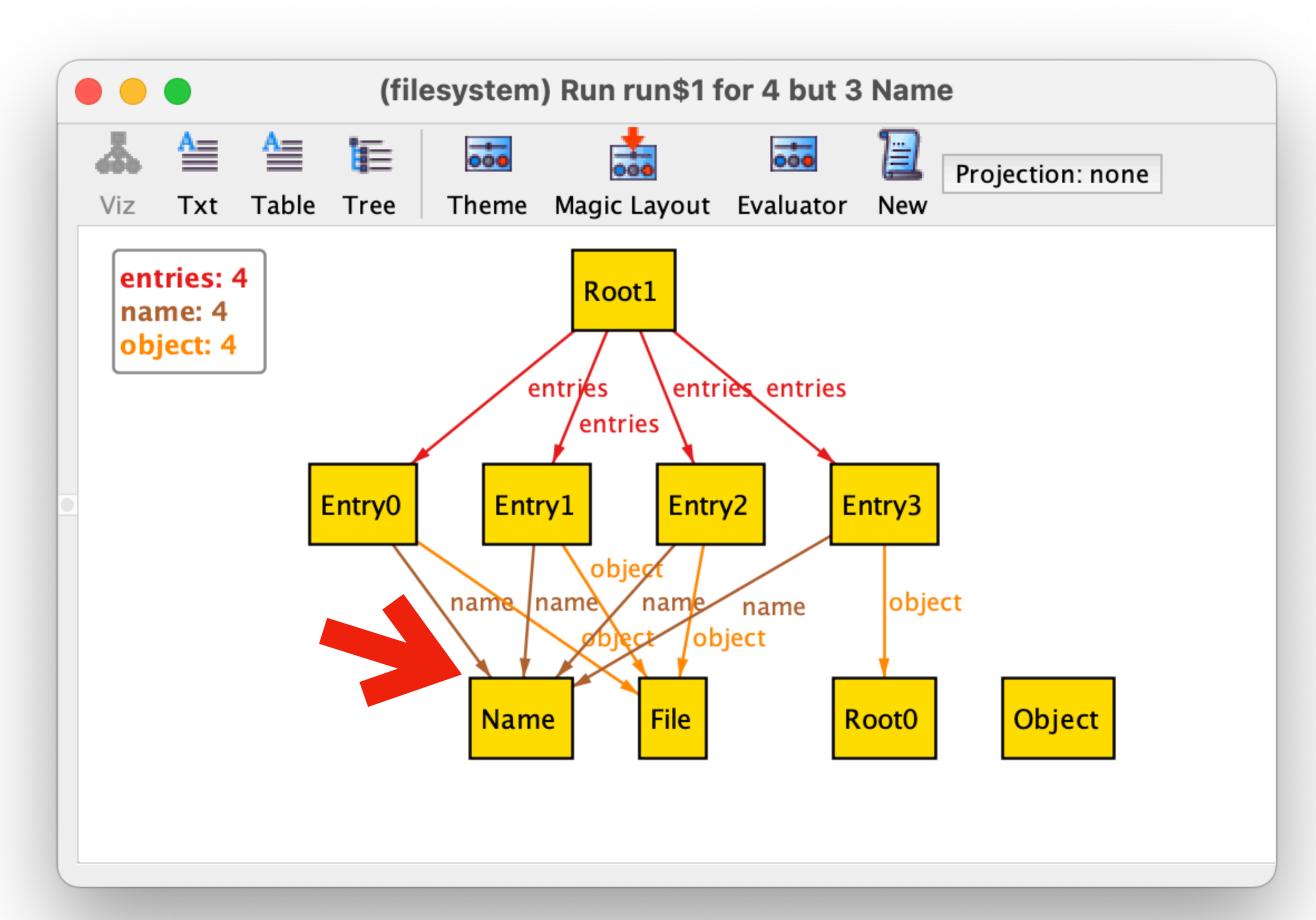
The constraints

- There are no other objects except directories and files
- All objects except the root are contained in at least one entry (at most one for the case of directories)
- There is only one root



The constraints

- There are no other objects except directories and files
- All objects except the root are contained in at least one entry (at most one for the case of directories)
- There is only one root
- Different entries in a directory must have different names



Abstract signatures

- All atoms in an abstract signature belong to one of its extensions
- The extensions partition the parent signature

```
abstract sig Object {}
sig Dir extends Object {
  entries : set Entry
}
sig File extends Object {}
```

Signature multiplicities

- Multiplicities can also be used in signature declarations
- In particular, a one sig denotes a constant

```
one sig Root extends Dir {}
```

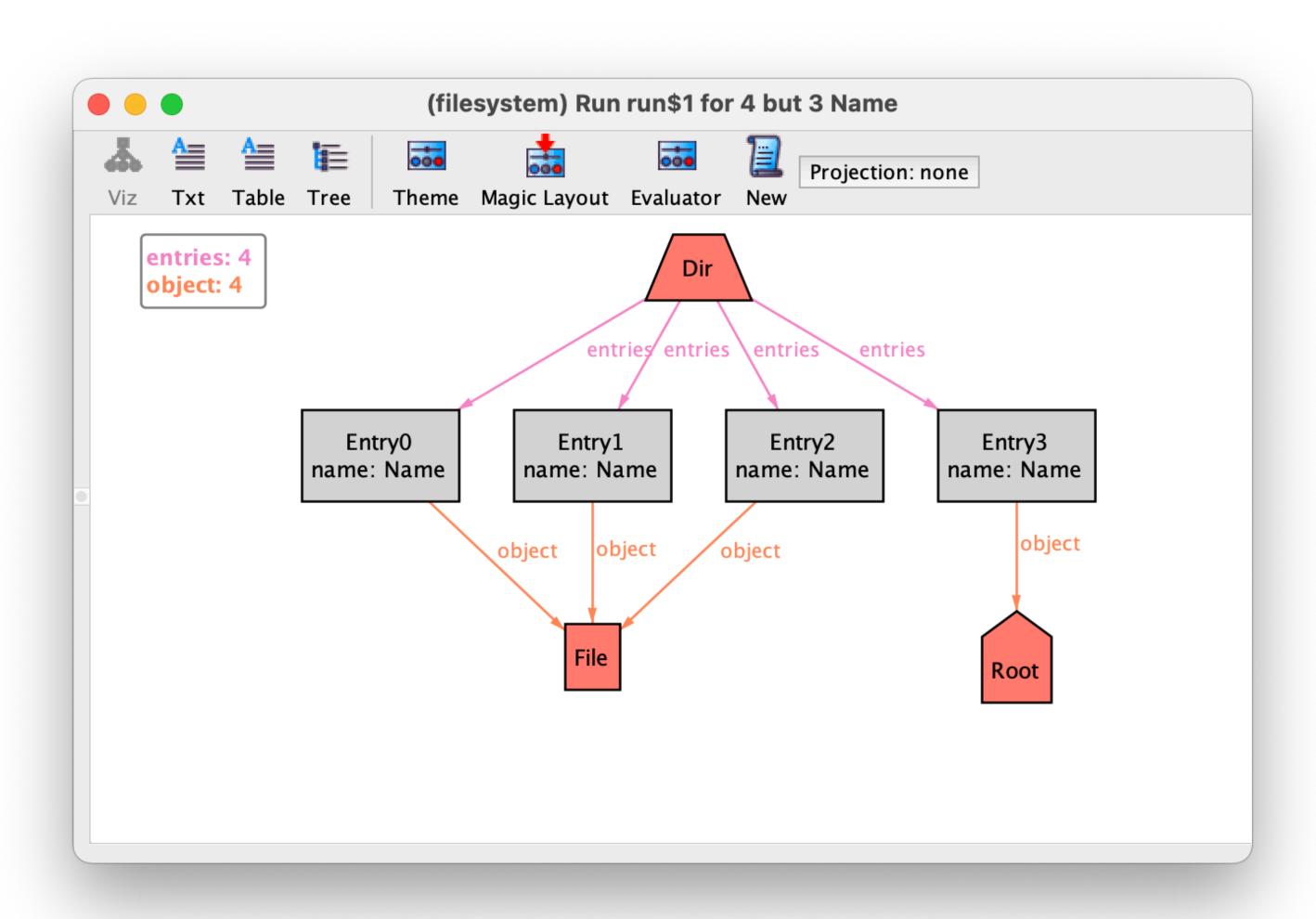
Themes

- The visualiser theme can be customised
- Customisation can ease the understanding and help validate the model
- It is possible to customise colours, shapes, visibility, ...

Theme customisation



Theme customisation



Relational logic

The constraints in FOL

```
fact {
   // All objects except the root are contained in at least one entry
   \forall o \cdot \mathsf{Object}(o) \land o \neq \mathsf{Root} \rightarrow \exists e \cdot \mathsf{object}(e,d)
   \forall e. \neg object(e, Root)
   // All directories are contained in at most one entry
   \forall d, e_1, e_2 \cdot \text{Dir}(d) \land \text{object}(e_1, d) \land \text{object}(e_2, d) \rightarrow e_1 = e_2
   // Different entries in a directory must have different names
   \forall d, n, e_1, e_2 \cdot \text{entries}(d, e_1) \land \text{entries}(d, e_2) \land \text{name}(e_1, n) \land \text{name}(e_2, n) \rightarrow e_1 = e_2
```

The constraints in FOL

```
fact {
   // All objects except the root are contained in at least one entry
   \forall o \cdot (o) \in \text{Object} \land o \neq \text{Root} \rightarrow \exists e \cdot (e, d) \in \text{object}
   \forall e.(e, \text{Root}) \notin \text{object}
   // All directories are contained in at most one entry
   \forall d, e_1, e_2 \cdot (d) \in \text{Dir} \land (e_1, d) \in \text{object} \land (e_2, d) \in \text{object} \rightarrow e_1 = e_2
   // Different entries in a directory must have different names
   \forall d, n, e_1, e_2 \cdot (d, e_1) \in \text{entries} \land (d, e_2) \in \text{entries} \land (e_1, n) \in \text{name} \land (e_2, n) \in \text{name} \rightarrow e_1 = e_2
```

Logical operators

```
\begin{array}{lll} & \neg \phi \\ \phi & \text{and } \psi \\ \phi & \text{or } \psi \\ \phi & \text{implies } \psi \\ \phi & \text{implies } \psi & \text{else } \theta \\ \phi & \text{iff } \psi \\ \end{array}
```

Logical operators

```
! \phi
\phi && \psi
\phi || \psi
\phi => \psi
\phi => \psi else \theta
\phi <=> \psi
```

$$\neg \varphi$$

$$\phi \land \psi$$

$$\phi \lor \psi$$

$$\phi \to \psi$$

$$(\phi \land \psi) \lor (\neg \phi \land \theta)$$

$$\phi \leftrightarrow \psi$$

Quantifiers

```
all x: univ \mid \phi \forall x \cdot \phi

all x: A \mid \phi all x: univ \mid x \text{ in } A \Rightarrow \phi

some x: univ \mid \phi \exists x \cdot \phi

some x: A \mid \phi some x: univ \mid x \text{ in } A \&\& \phi
```

Atomic formulas

$$x = y$$

$$x = y$$

$$x_1$$
 ->···-> x_n in R
 x_1 ->···-> x_n not in R

$$x = y$$
 $x \neq y$

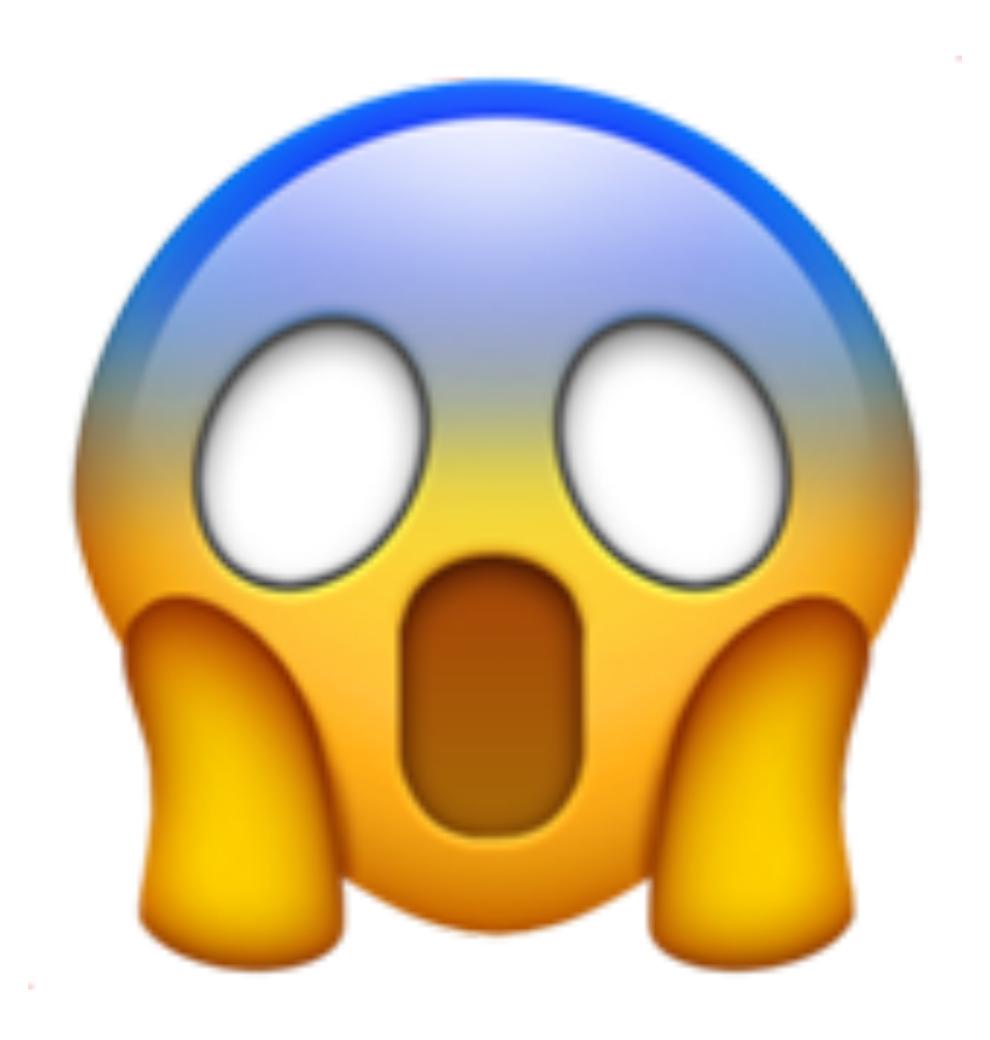
$$(x_1, ..., x_n) \in R$$
$$(x_1, ..., x_n) \notin R$$

The constraints in Alloy

```
fact {
    // All objects except the root are contained in at least one entry
    all o : univ | o in Object and o != Root implies some e : univ | e->o in object
    all o : univ | o->Root not in object

    // All directories are contained in at most one entry
    all d,el,e2 : univ | d in Dir and el->d in object and e2->d in object implies el = e2

    // Different entries in a directory must have different names
    all d,n,el,e2 : univ | d->el in entries and d->e2 in entries and el->n in name and e2->n in name implies el = e2
}
```



Relational logic

- Relational logic extends FOL with:
 - Derived atomic formulas, namely cardinality checks
 - Derived operators to combine predicates (relations) into more complex predicates
 - Transitive and reflexive closures, which cannot be expressed in FOL

Atomic formulas

```
// Subset  R \text{ in } S \qquad R \subseteq S \qquad \forall x_1, ..., x_n \cdot (x_1, ..., x_n) \in R \rightarrow (x_1, ..., x_n) \in S   R \text{ not in } S \qquad R \nsubseteq S   // \text{ Set equality}   R = S \qquad R = S \qquad R \subseteq S \land S \subseteq R   R != S \qquad R \neq S
```

Atomic formulas

```
// Cardinality checks some R |R| > 0 \exists x_1, ..., x_n \cdot (x_1, ..., x_n) \in R no R |R| = 0 \forall x_1, ..., x_n \cdot (x_1, ..., x_n) \notin R lone R |R| < 2 one R |R| = 1
```

Set operators

```
// Union R+S \qquad R\cup S \qquad (x_1,...,x_n)\in (R+S) \leftrightarrow (x_1,...,x_n)\in R \vee (x_1,...,x_n)\in S // Intersection R \& S \qquad R\cap S \qquad (x_1,...,x_n)\in (R \& S) \leftrightarrow (x_1,...,x_n)\in R \wedge (x_1,...,x_n)\in S // Difference R-S \qquad R\backslash S \qquad (x_1,...,x_n)\in (R-S) \leftrightarrow (x_1,...,x_n)\in R \wedge (x_1,...,x_n)\notin S
```

Relational constants

```
// Universe univ \forall x \cdot (x) \in \mathbf{univ} // Empty set none \varnothing \forall x \cdot (x) \notin \mathbf{none} // Identity iden id \forall x_1, x_2 \cdot (x_1, x_2) \in \mathbf{iden} \leftrightarrow x_1 = x_2
```

Relational operators

```
// Cartesian product
R \to S R \times S (x_1, ..., x_n, y_1, ..., y_m) \in (R \to S) \leftrightarrow (x_1, ..., x_n) \in R \land (y_1, ..., y_m) \in S
// Transpose or converse
           R^{\circ} \qquad (x_1, x_2) \in (\neg R) \leftrightarrow (x_2, x_1) \in R
~R
// Range restriction
R:>A
                     (x_1, ..., x_n) \in (R :> A) \leftrightarrow (x_1, ..., x_n) \in R \land (x_n) \in A
     Domain restriction
A <: R
                     (x_1, ..., x_n) \in (A <: R) \leftrightarrow (x_1, ..., x_n) \in R \land (x_1) \in A
```

Inclusion vs subset

```
all x : Dir | x in Object

all x : univ | x in Dir implies x in Object

\forall x.(x) \in \text{Dir} \rightarrow (x) \in \text{Object}
\forall x.\{(x)\} \subseteq \text{Dir} \rightarrow \{(x)\} \subseteq \text{Object}
```

Inclusion vs subset

```
all x : Entry | some y : Name | x->y in name \forall x.(x) \in \text{Entry} \to \exists y.(y) \in \text{Name} \land (x,y) \in \text{name} \forall x.\{(x)\} \subseteq \text{Entry} \to \exists y.\{(y)\} \subseteq \text{Name} \land \{(x)\} \times \{(y)\} \subseteq \text{name} \forall x.\{(x)\} \subseteq \text{Entry} \to \exists y.\{(y)\} \subseteq \text{Name} \land \{(x,y)\} \subseteq \text{name}
```

$$R \cdot S$$

$$S \circ R$$

$$(x_1, ..., x_{n-1}, y_2, ..., y_m) \in (R . S)$$

$$\longleftrightarrow$$

$$\exists z \cdot (x_1, ..., x_{n-1}, z) \in R \land (z, y_2, ..., y_m) \in S$$

entries		
Root	Entry0	
Root	Entry2	
Dir	Entry1	
Dir	Entry3	

name		
Entry0	Name0	
Entry1	Name1	
Entry2	Name1	
Entry3	Name1	

entries		
Root	Entry0	
Root	Entry2	
Dir	Entry1	
Dir	Entry3	

name		
Entry0	Name0	
Entry1	Name1	
Entry2	Name1	
Entry3	Name1	

entries . name

ent	ries	na	me
Root	Entry0	Entry0	Name0
Root	Entry2	Entry1	Name1
Dir	Entry1	Entry2	Name1
Dir	Entry3	Entry3	Name1

entries	. name
Root	Name0

ent	ries	na	me
Root	Entry0	Entry0	Name0
Root	Entry2	Entry1	Name1
Dir	Entry1	Entry2	Name1
Dir	Entry3	Entry3	Name1

entries	. name
Root	Name0
Root	Name1

ent	ries	na	me
Root	Entry0	Entry0	Name0
Root	Entry2	Entry1	Name1
Dir	Entry1	Entry2	Name1
Dir	Entry3	Entry3	Name1

entries	. name
Root	Name0
Root	Name1
Dir	Name1

entries	
Root	Entry0
Root	Entry2
Dir	Entry1
Dir	Entry3

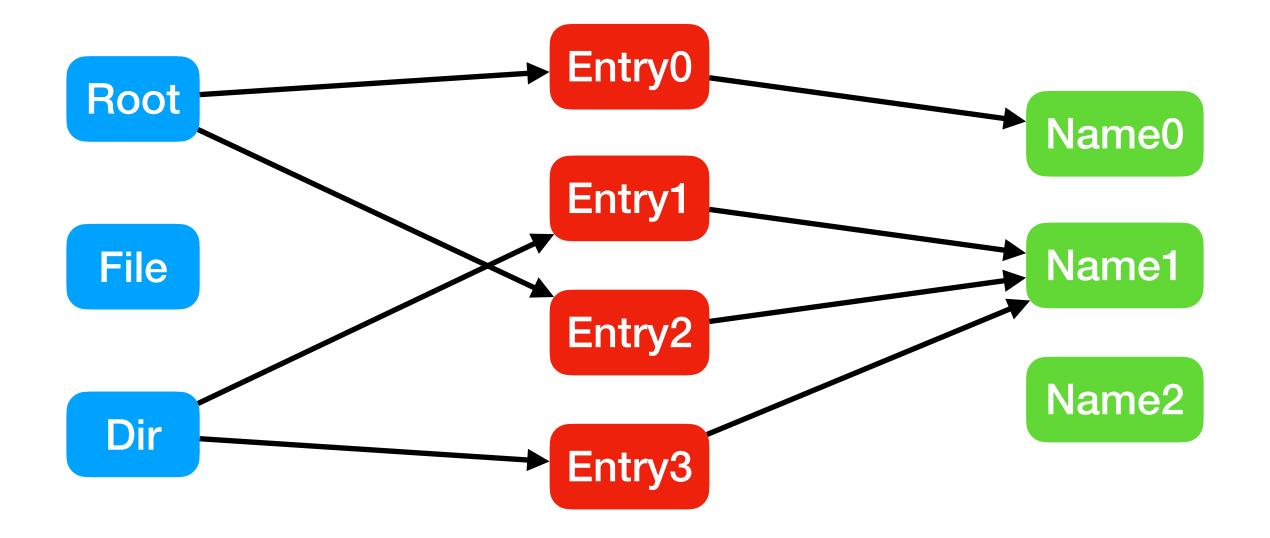
name		
Entry0	Name0	
Entry1	Name1	
Entry2	Name1	
Entry3	Name1	

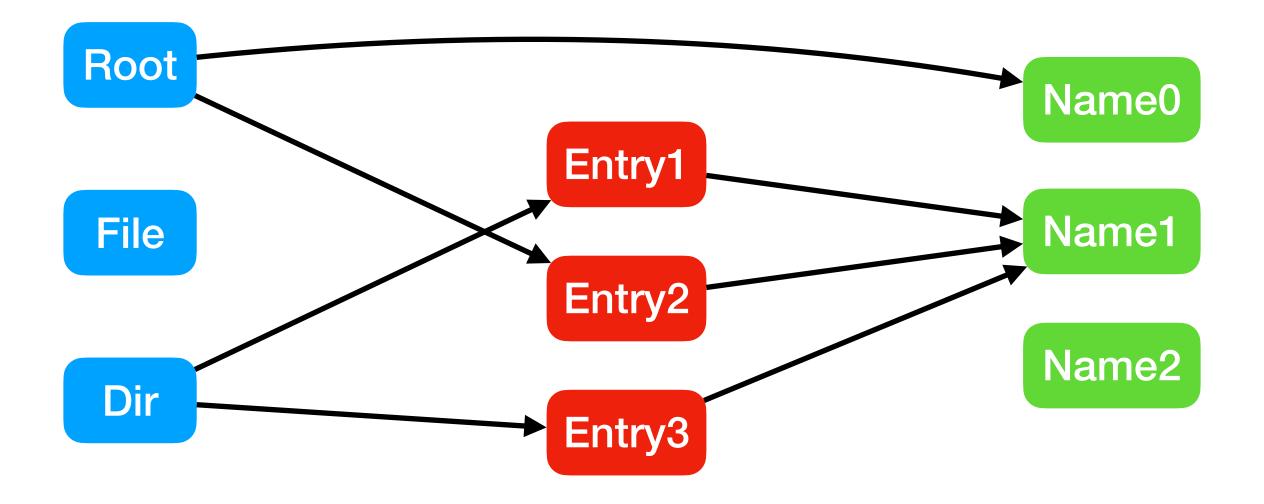
entries	. name
Root	Name0
Root	Name1
Dir	Name1

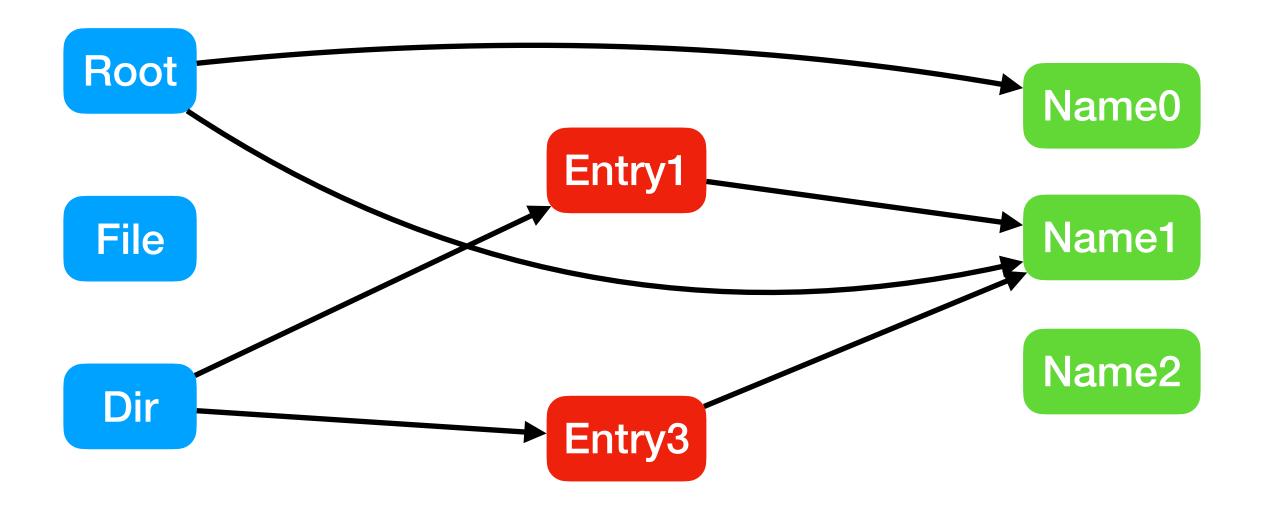
entries		
Root	Entry0	
Root	Entry2	
Dir	Entry1	
Dir	Entry3	

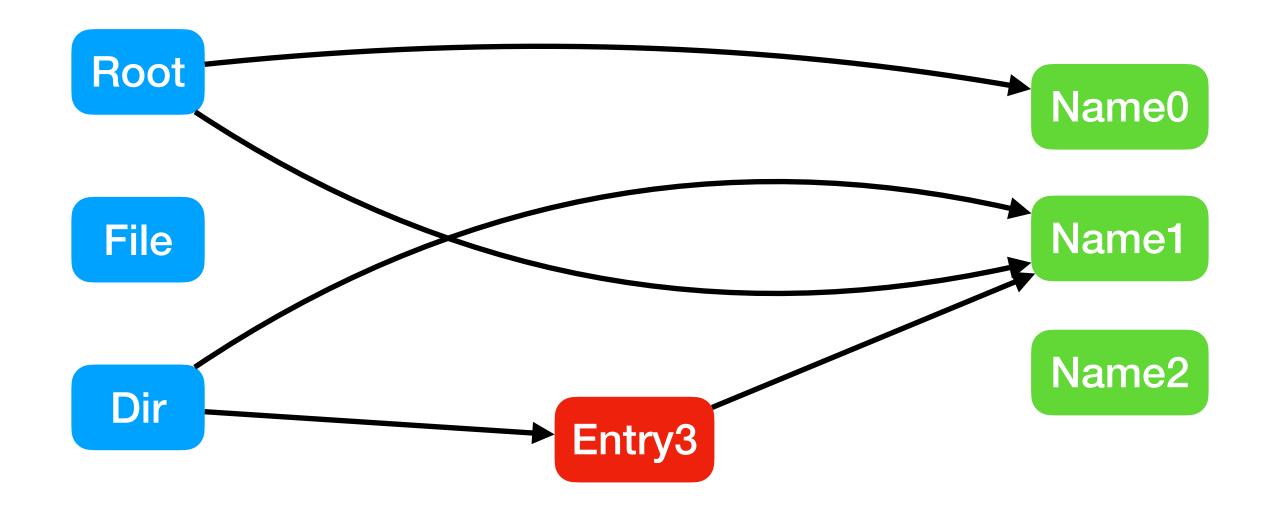
name	
Entry0	Name0
Entry1	Name1
Entry2	Name1
Entry3	Name1

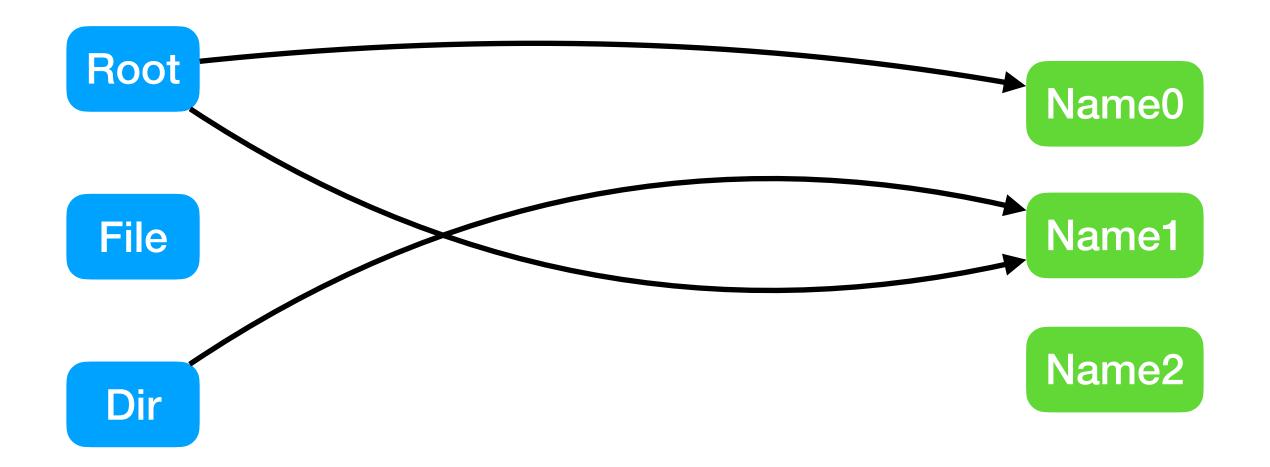
entries	. name
Root	Name0
Root	Name1
Dir	Name1











entries	
Root	Entry0
Root	Entry2
Dir	Entry1
Dir	Entry3

Entry0 Entry1 Entry2 Entry3

entries		
Root	Entry0	
Root	Entry2	
Dir	Entry1	
Dir	Entry3	

Entry Entry0 Entry1 Entry2 Entry3

entries . Entry

ent	ries	Entry
Root	Entry0	Entry0
Root	Entry2	Entry1
Dir	Entry1	Entry2
Dir	Entry3	Entry3

entries . Entry
Root

ent	ries	Entry
Root	Entry0	Entry0
Root	Entry2	Entry1
Dir	Entry1	Entry2
Dir	Entry3	Entry3

entries . Entry
Root

ent	ries	Entry
Root	Entry0	Entry0
Root	Entry2	Entry1
Dir	Entry1	Entry2
Dir	Entry3	Entry3



ent	ries	Entry
Root	Entry0	Entry0
Root	Entry2	Entry1
Dir	Entry1	Entry2
Dir	Entry3	 Entry3

entries . Entry
Root
Dir

entries		
Root	Entry0	
Root	Entry2	
Dir	Entry1	
Dir	Entry3	

Entry
Entry0
Entry1
Entry2
Entry3

```
entries . Entry
Root
Dir
```

Root

Root

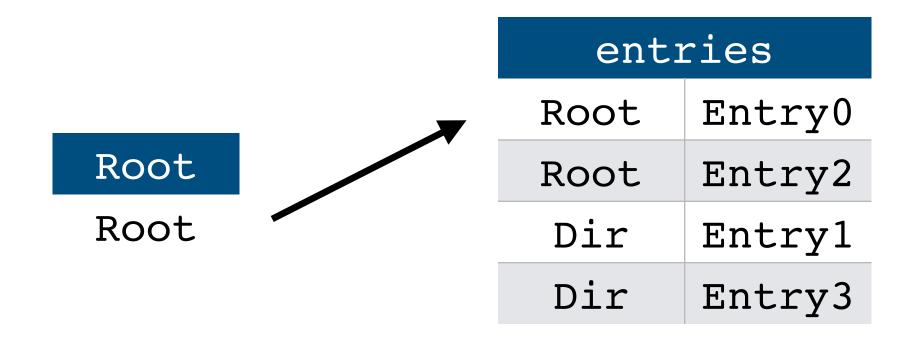
entries		
Root	Entry0	
Root	Entry2	
Dir	Entry1	
Dir	Entry3	

Root

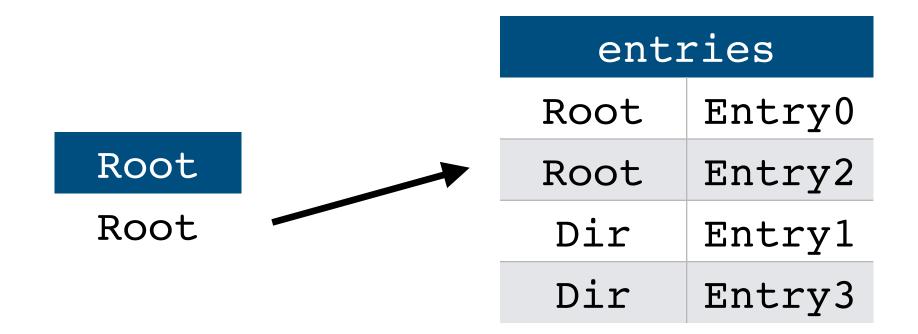
Root

entries		
Root	Entry0	
Root	Entry2	
Dir	Entry1	
Dir	Entry3	

Root . entries



Root . entries
Entry0



Root . entries
Entry0
Entry2

Root

Root

entries		
Root	Entry0	
Root	Entry2	
Dir	Entry1	
Dir	Entry3	

Root . entries

Entry0

Entry2

```
all o: univ o->Root not in object
```

```
all o: univ o->Root not in object
```

```
all o: univ o not in object.Root
```

```
all o : univ | o->Root not in object
all o : univ | o not in object.Root
no object.Root
```

all o: univ | o in Object and o! = Root implies some e: univ | e->o in object

```
all o : univ | o in Object and o != Root implies some e : univ | e->o in object all o : univ | o in Object and o != Root implies some e : univ | e in object.o
```

```
all o : univ | o in Object and o != Root implies some e : univ | e->o in object
all o : univ | o in Object and o != Root implies some e : univ | e in object.o
all o : univ | o in Object and o != Root implies some object.o
```

```
all o : univ | o in Object and o != Root implies some e : univ | e->o in object

all o : univ | o in Object and o != Root implies some e : univ | e in object.o

all o : univ | o in Object and o != Root implies some object.o

all o : univ | o in Object and o not in Root implies some object.o
```

```
all o : univ | o in Object and o != Root implies some e : univ | e->o in object
all o : univ | o in Object and o != Root implies some e : univ | e in object.o

all o : univ | o in Object and o != Root implies some object.o

all o : univ | o in Object and o not in Root implies some object.o

all o : univ | o in Object-Root implies some object.o
```

```
all o : univ | o in Object and o != Root implies some e : univ | e->o in object
all o : univ | o in Object and o != Root implies some e : univ | e in object.o
all o : univ | o in Object and o != Root implies some object.o
all o : univ | o in Object and o not in Root implies some object.o
all o : univ | o in Object-Root implies some object.o
all o : Object-Root | some object.o
```

all d,e1,e2: univ | d in Dir and e1->d in object and e2->d in object implies e1 = e2

```
all d,e1,e2 : univ | d in Dir and e1->d in object and e2->d in object implies e1 = e2
all d : univ | d in Dir implies all e1,e2 : univ | e1->d in object and e2->d in object implies e1 = e2
```

```
all d,e1,e2 : univ | d in Dir and e1->d in object and e2->d in object implies e1 = e2
all d : univ | d in Dir implies all e1,e2 : univ | e1->d in object and e2->d in object implies e1 = e2
all d : Dir | all e1,e2 : univ | e1->d in object and e2->d in object implies e1 = e2
```

```
all d,e1,e2 : univ | d in Dir and e1->d in object and e2->d in object implies e1 = e2
all d : univ | d in Dir implies all e1,e2 : univ | e1->d in object and e2->d in object implies e1 = e2
all d : Dir | all e1,e2 : univ | e1->d in object and e2->d in object implies e1 = e2
all d : Dir | all e1,e2 : univ | e1 in object.d and e2 in object.d implies e1 = e2
```

```
all d,e1,e2 : univ | d in Dir and e1->d in object and e2->d in object implies e1 = e2
all d : univ | d in Dir implies all e1,e2 : univ | e1->d in object and e2->d in object implies e1 = e2
all d : Dir | all e1,e2 : univ | e1->d in object and e2->d in object implies e1 = e2
all d : Dir | all e1,e2 : univ | e1 in object.d and e2 in object.d implies e1 = e2
all d : Dir | lone object.d
```

all d,n,e1,e2: univ | d->e1 in entries and d->e2 in entries and e1->n in name and e2->n in name implies e1 = e2

```
all d,n,e1,e2 : univ | d->e1 in entries and d->e2 in entries and e1->n in name and e2->n in name implies e1 = e2

all d,n,e1,e2 : univ | e1 in entries.d and e2 in entries.d and e1 in name.n and e2 in name.n implies e1 = e2
```

```
all d,n,e1,e2 : univ | d->e1 in entries and d->e2 in entries and e1->n in name and e2->n in name implies e1 = e2

all d,n,e1,e2 : univ | e1 in entries.d and e2 in entries.d and e1 in name.n and e2 in name.n implies e1 = e2

all d,n,e1,e2 : univ | e1 in entries.d and e1 in name.n and e2 in entries.d and e2 in name.n implies e1 = e2
```

```
all d,n,e1,e2 : univ | d->e1 in entries and d->e2 in entries and e1->n in name and e2->n in name implies e1 = e2

all d,n,e1,e2 : univ | e1 in entries.d and e2 in entries.d and e1 in name.n and e2 in name.n implies e1 = e2

all d,n,e1,e2 : univ | e1 in entries.d and e1 in name.n and e2 in entries.d and e2 in name.n implies e1 = e2

all d,n,e1,e2 : univ | e1 in (entries.d & name.n) and e2 in (entries.d & name.n) implies e1 = e2
```

From FOL to RL

```
all d,n,e1,e2: univ | d->e1 in entries and d->e2 in entries and e1->n in name and e2->n in name implies e1 = e2

all d,n,e1,e2: univ | e1 in entries.d and e2 in entries.d and e1 in name.n and e2 in name.n implies e1 = e2

all d,n,e1,e2: univ | e1 in entries.d and e1 in name.n and e2 in entries.d and e2 in name.n implies e1 = e2

all d,n,e1,e2: univ | e1 in (entries.d & name.n) and e2 in (entries.d & name.n) implies e1 = e2

all d,n: univ | lone (entries.d & name.n)
```

From FOL to RL

```
all d,n,e1,e2: univ | d->e1 in entries and d->e2 in entries and e1->n in name and e2->n in name implies e1 = e2

all d,n,e1,e2: univ | e1 in entries.d and e2 in entries.d and e1 in name.n and e2 in name.n implies e1 = e2

all d,n,e1,e2: univ | e1 in entries.d and e1 in name.n and e2 in entries.d and e2 in name.n implies e1 = e2

all d,n,e1,e2: univ | e1 in (entries.d & name.n) and e2 in (entries.d & name.n) implies e1 = e2

all d,n: univ | lone (entries.d & name.n)

all d: Dir, n: Name | lone (entries.d & name.n)
```

The constraints in Alloy

```
fact {
 // All objects except the root are contained in at least one entry
 all o: Object - Root | some object.o
 no object.Root
 // All directories are contained in at most one entry
 all d: Dir | lone object.d
 // Different entries in a directory must have different names
 all d: Dir, n: Name | lone (d.entries & name.n)
```



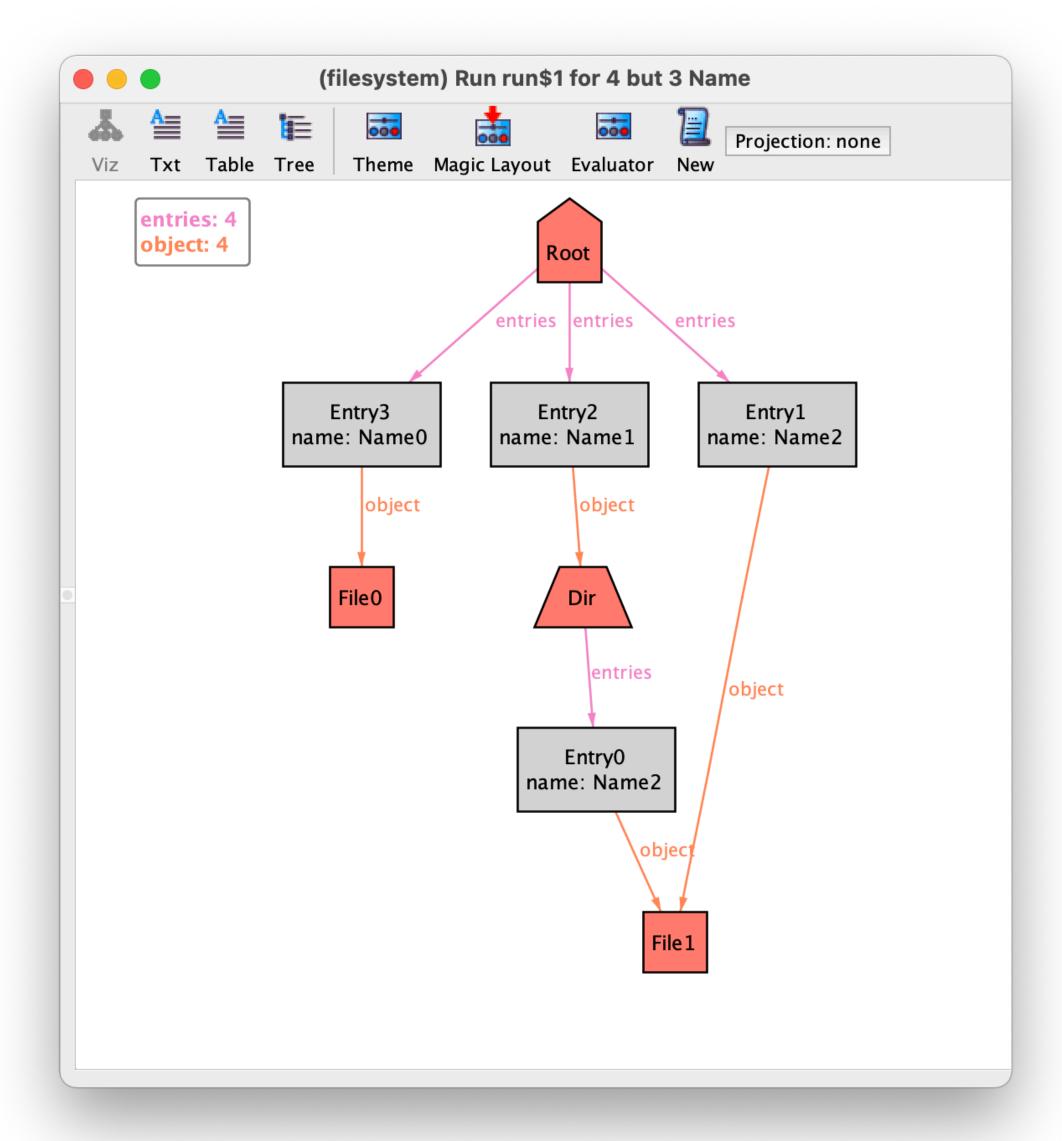
```
// First order style
all x,y : Entry, n : Name | x->n in name and y->n in name implies x=y
```

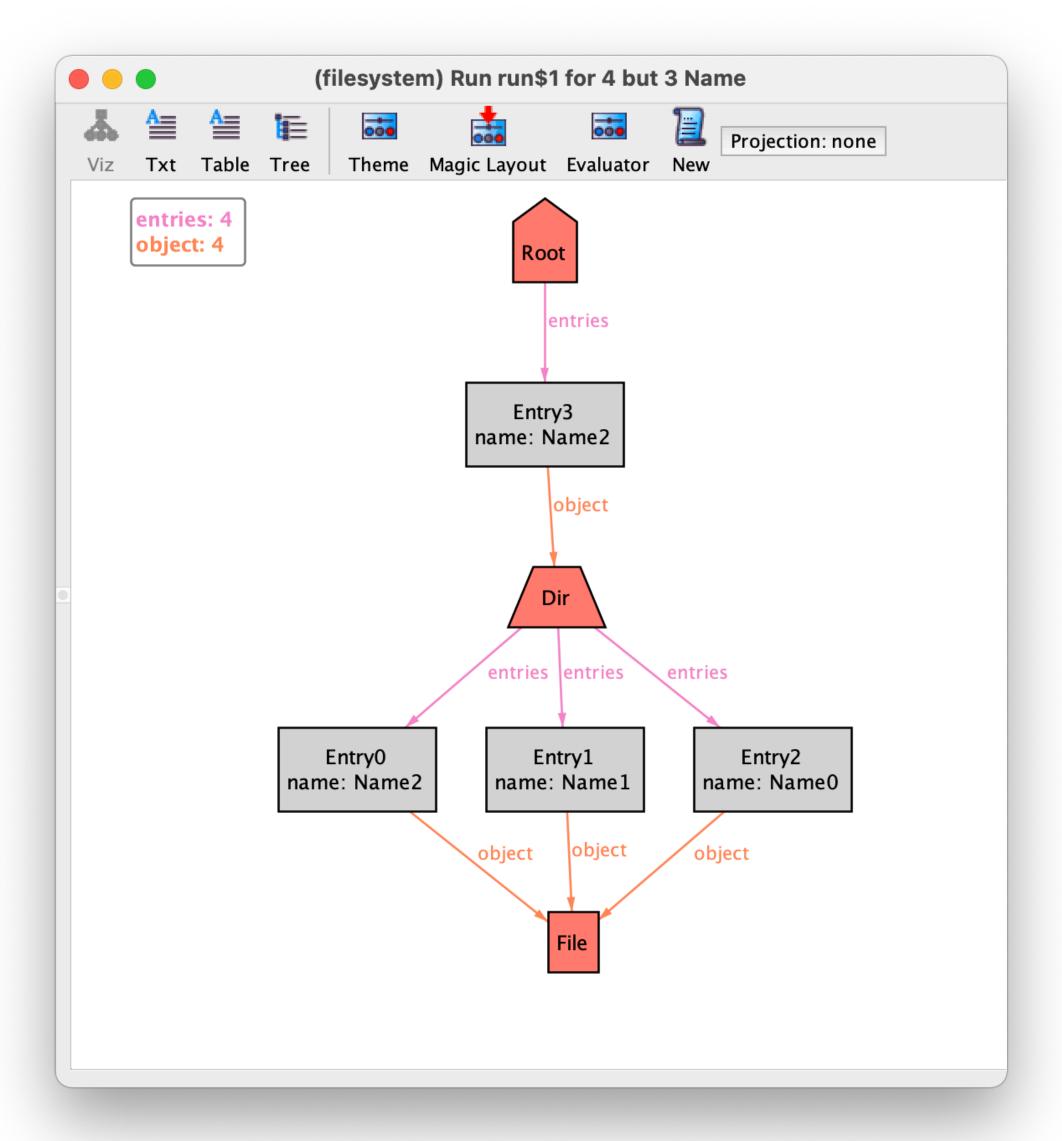
```
// First order style
all x,y : Entry, n : Name | x->n in name and y->n in name implies x=y
// Relational or navigational style
all n : Name | lone name.n
```

```
// First order style
all x,y : Entry, n : Name | x->n in name and y->n in name implies x=y
// Relational or navigational style
all n : Name | lone name.n
// Point-free style
name.~name in iden
```

Verification

Some instances



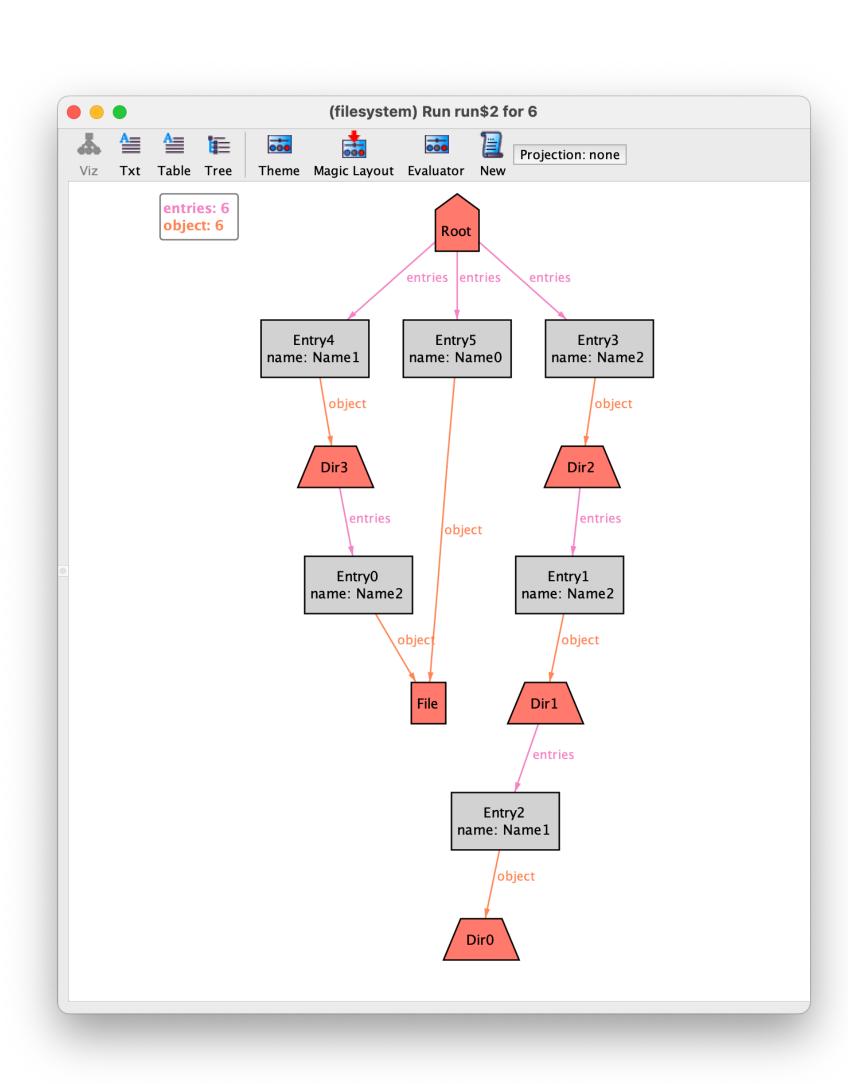


Assertions

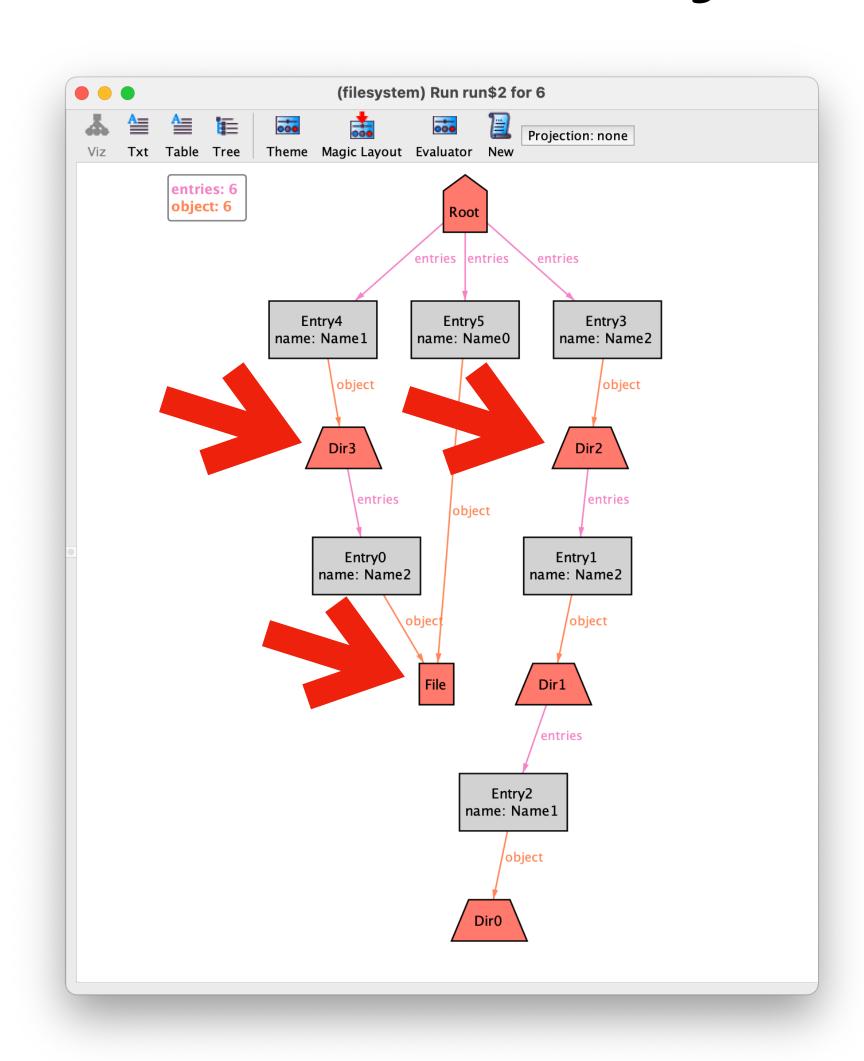
Assertions are named constraints to be checked

```
assert NoPartitions {
    // All objects are reachable from the root
    ???
}
```

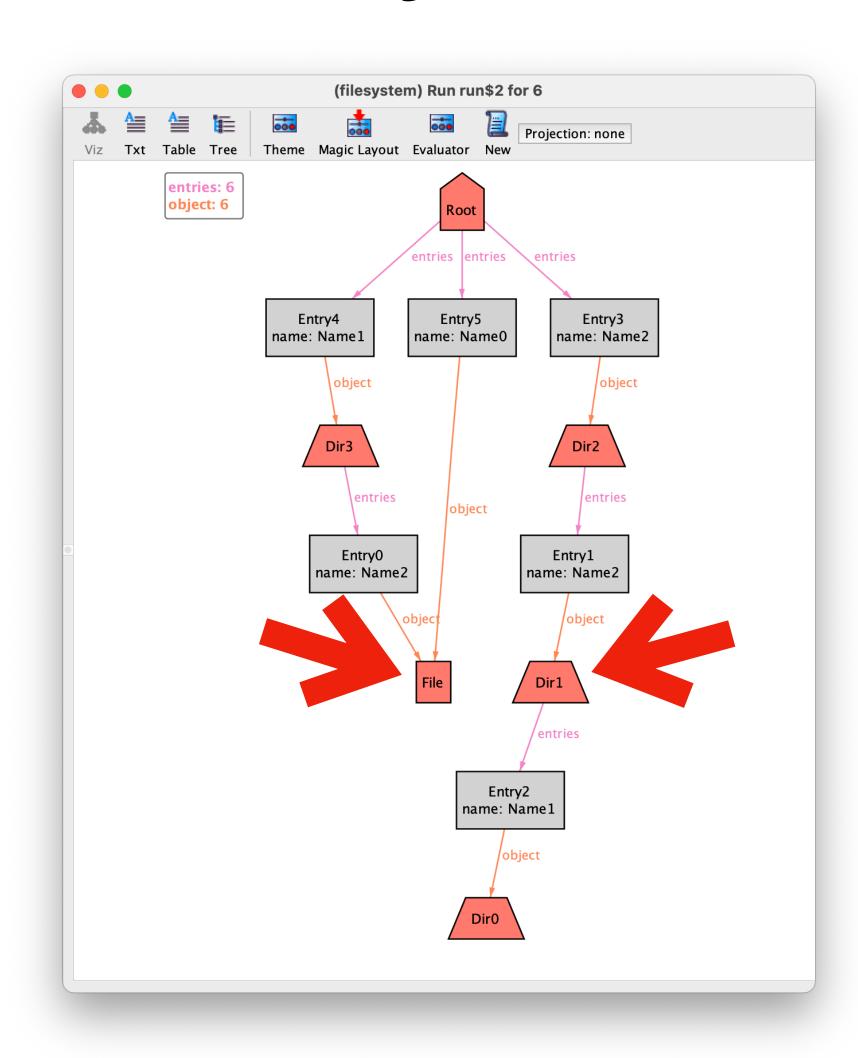
check NoPartitions



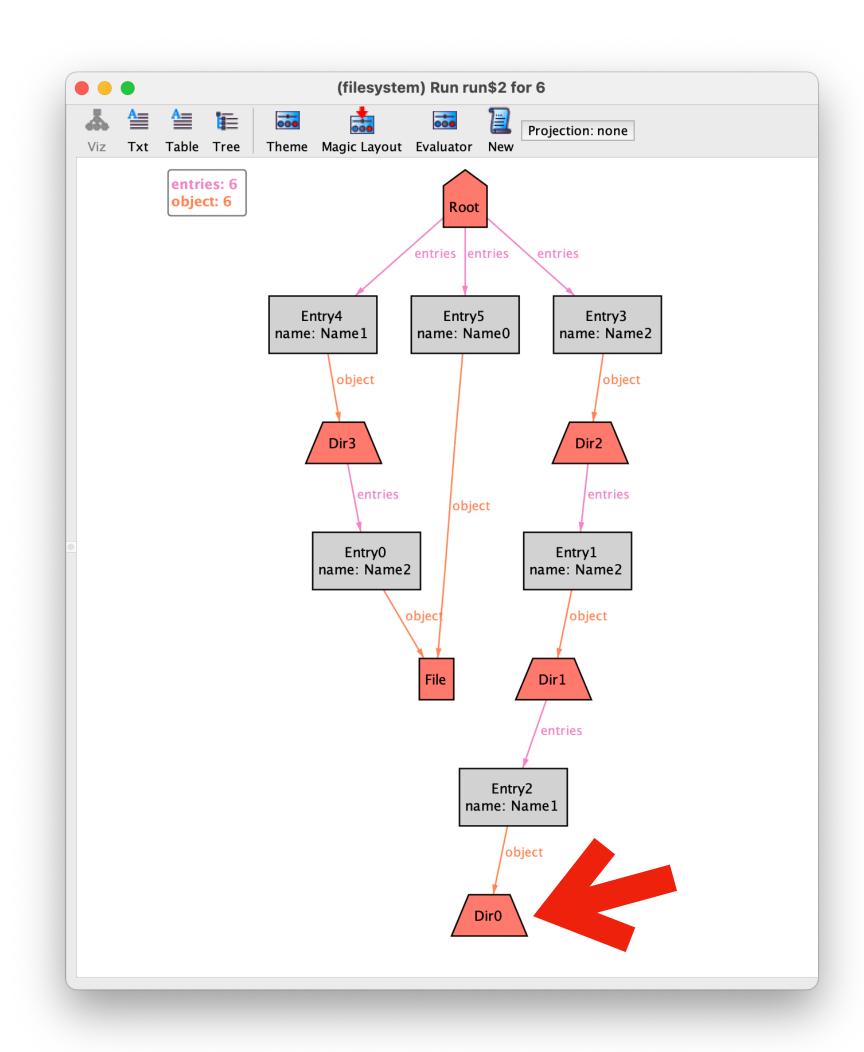
Root.entries.object



Root.entries.object.entries.object



Root.entries.object.entries.object.entries.object



Closures

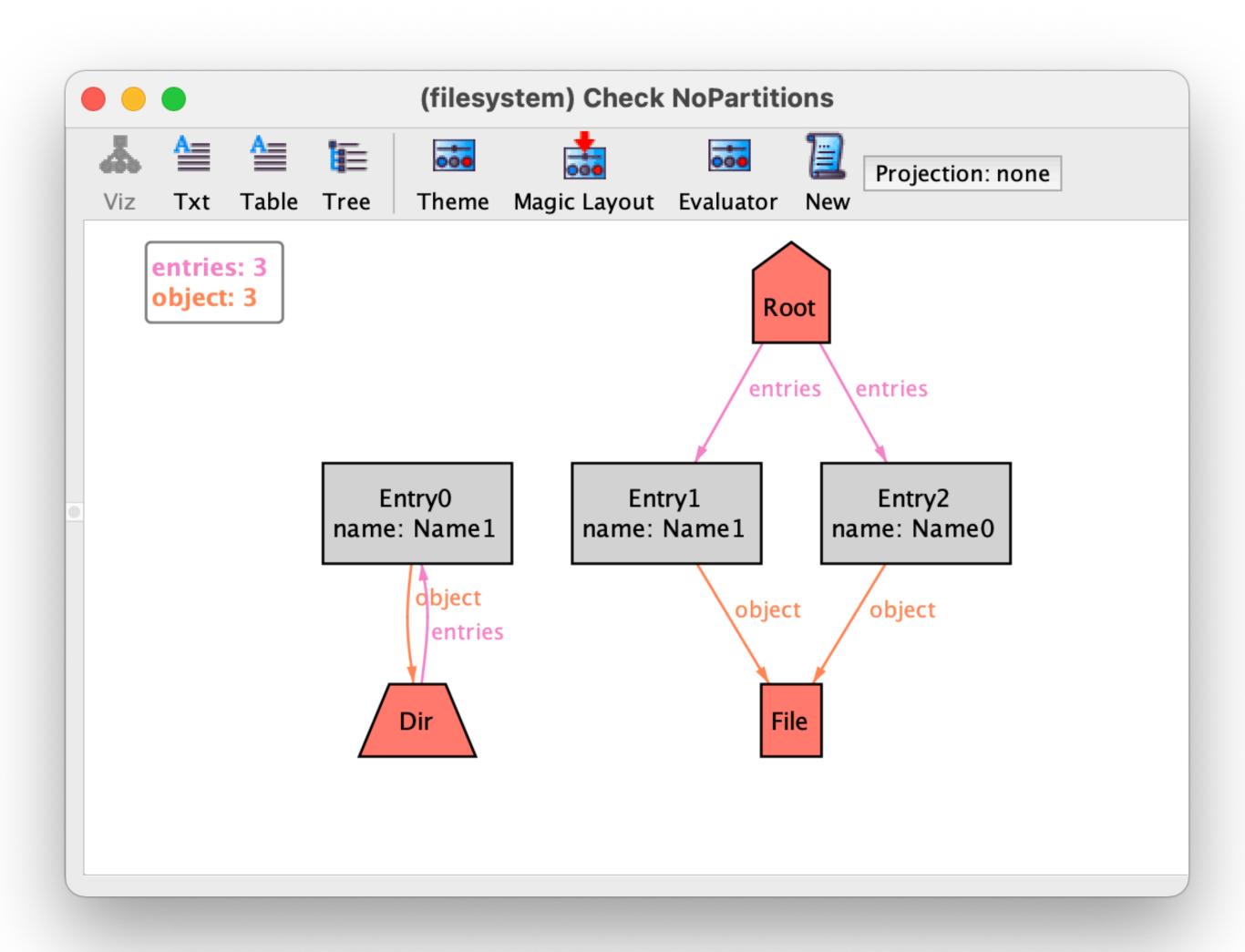
```
// Transitive closure
^{R}R = R + R.R + R.R.R + R.R.R.R + ...
// Reflexive transitive closure
^{R}R = ^{R}R + iden
```

The desired assertion

```
assert NoPartitions {
    // All objects are reachable from the root
    Object in Root.*(entries.object)
}
```

check NoPartitions

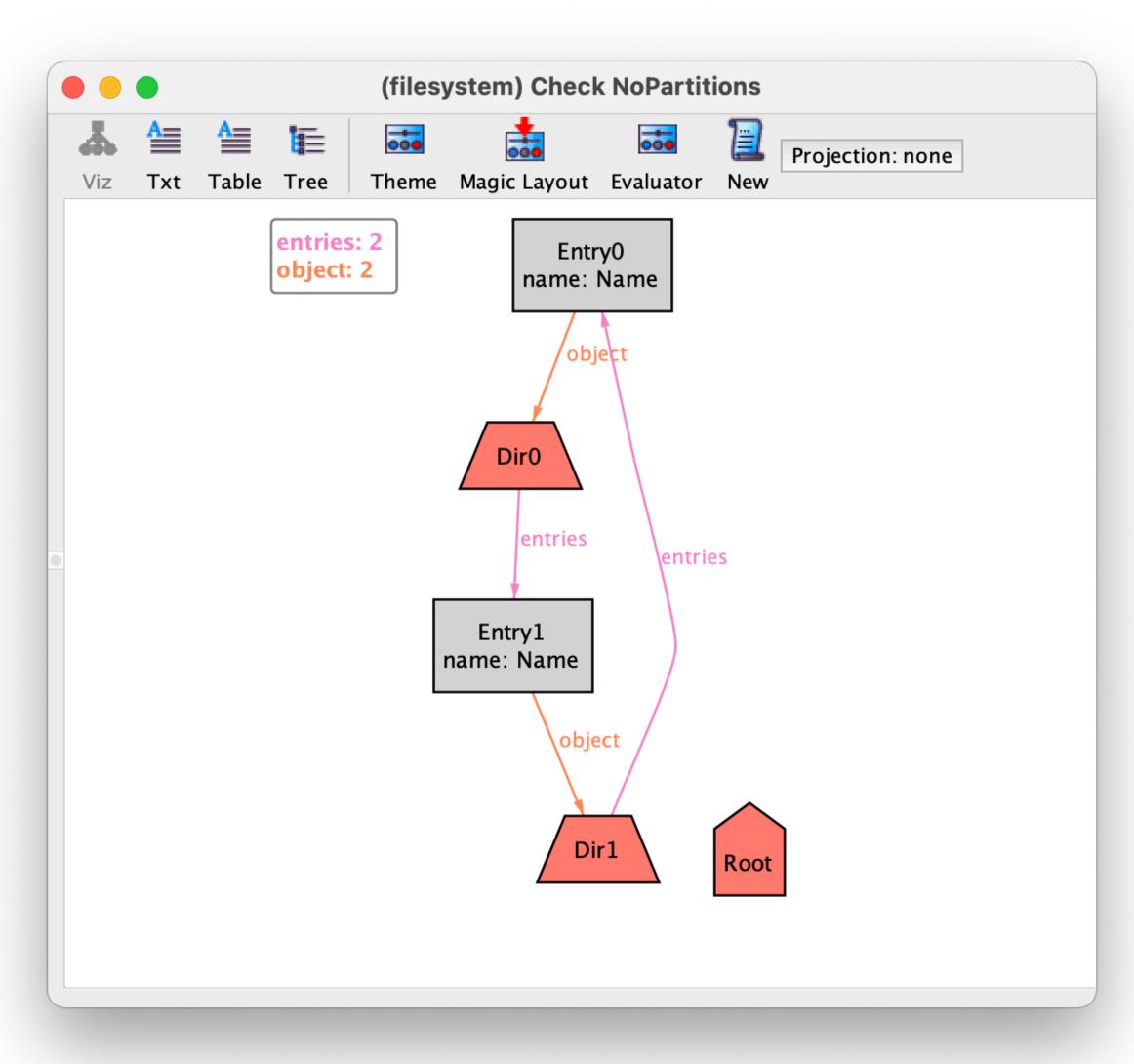
A counter-example



The missing constraint

```
fact {
 // All objects except the root are contained in at least one entry
 all o : Object - Root | some object.o
 no object.Root
 // All directories are contained in at most one entry
 all d: Dir | lone object.d
 // Different entries in a directory must have different names
 all d: Dir, n: Name | lone (d.entries & name.n)
 // A directory cannot be contained in itself
 all d: Dir | d not in d.entries.object
```

Another counter-example



The missing constraint

```
fact {
 // All objects except the root are contained in at least one entry
 all o : Object - Root | some object.o
 no object.Root
 // All directories are contained in at most one entry
 all d: Dir | lone object.d
 // Different entries in a directory must have different names
 all d: Dir, n: Name | lone (d.entries & name.n)
 // A directory cannot be contained in itself
 all d: Dir | d not in d.^(entries.object)
```

Executing "Check NoPartitions"

Solver=sat4j Bitwidth=4 MaxSeq=4 SkolemDepth=1 Symmetry=20 Mode=batch 586 vars. 37 primary vars. 860 clauses. 3ms.

No counterexample found. Assertion may be valid. 2ms.



Increasing confidence

Increase the scope of check commands

```
check NoPartitions for 6
```

- Use run commands to check consistency
- Verify that specific scenarios are possible

```
run {
    // An empty file system
    Object = Root
}
```