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## **FORMAL SOFTWARE DESIGN WITH ALLOY AND ELECTRUM**

### **ANALYSIS**

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Carnegie Mellon University

3rd World Congress on Formal Methods, Porto, Portugal, October 2019

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**OPERATIONS**

## OPERATIONS AS PREDICATES

Back to: Simple social network

```
sig SocialNetwork {  
  friends : User -> User,  
  posts : User -> Post  
}
```

```
pred addPost[n1, n2 : SocialNetwork, u : User, p : Post] {  
  // precondition  
  // post condition  
  n2.posts = n1.posts + u -> p  
  // frame condition  
  n2.friends = n1.friends  
}
```

## SIMULATING AN OPERATION

```
run executeAdd {  
    some n1, n2 : SocialNetwork, u : User, p : Post] |  
        addPost[n1,n2,u,p]  
}
```

## SCOPES

```
run executeAdd {  
    some n1, n2 : SocialNetwork, u : User, p : Post] |  
        addPost[n1,n2,u,p]  
} for 5 but 3 User, exactly 2 SocialNetwork
```

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**ANALYSIS**

## ANALYSIS IN ALLOY

- Check:
  - ▶ Consistency of a specification
  - ▶ Invariants
  - ▶ Algebraic properties of operations
  - ▶ Refinement
  - ▶ Temporal properties

## INVARIANT CHECK

```
check addPostPreservesInvariant {  
    all n1, n2 : SocialNetwork, u : User, p : Post] |  
        invariant[n1] and addPost[n1,n2,u,p] implies  
            invariant[n2]  
}
```



## PROPERTY CHECKING AS CONSTRIANT SOLVING

```
check addPostPreservesInvariant {  
    all n1, n2 : SocialNetwork, u : User, p : Post] |  
        invariant[n1] and addPost[n1,n2,u,p] implies  
            invariant[n2]  
}
```

is equal to

```
run addPostViolatesInvariant {  
    some n1, n2 : SocialNetwork, u : User, p : Post] |  
        invariant[n1] and addPost[n1,n2,u,p] and  
            invariant[n2]  
}
```

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## CHECKING ALGEBRAIC PROPERTIES

## ALGEBRAIC PROPERTIES

If we add a post and immediately delete it, do we end up in the original state?

```
check addThenDeleteIsUndo {  
  all n1, n2, n3 : SocialNetwork, u : User, p : Post |  
    invariant[n1] and  
    addPost[n1,n2,u,p] and delPost[n2,n3,u,p] implies  
      n1.posts = n3.posts  
}
```

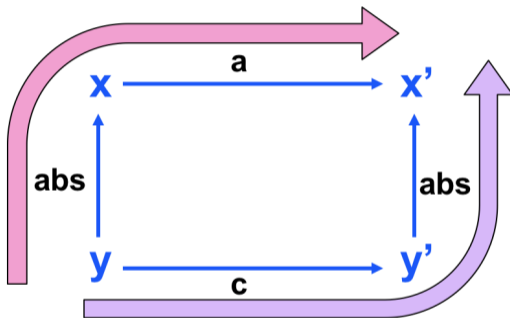
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**REFINEMENT**

## COMMUTING DIAGRAM

Is the distributed social network a correct implementation of the simple social network?

# COMMUTING DIAGRAM



where  $x = \alpha(y)$  ;  $x' = \alpha(y')$

## ABSTRACTION FUNCTION

```
fun abs[c : DistributedSN] : SocialNetwork {  
  { a : SocialNetwork |  
    a.posts = c.servers.posts and  
    a.friends = c.friends }  
}
```

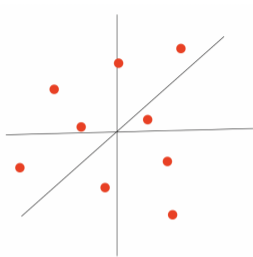
## REFINEMENT CHECK

```
assert AddPostRefinement {  
  all a1, a2 : SocialNetwork, c1, c2 : DistributedSN,  
    u : User, p : Post |  
    addPostDistributed[c1, c2, u, p] and  
    a1 = abs[c1] and a2 = abs[c2] implies  
      addPost[a1, a2, u, p]  
}
```

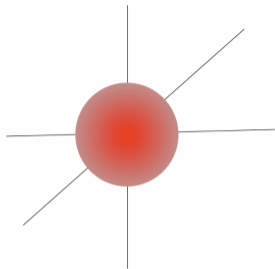
**check** AddPostRefinement



## BRIEF THEORY BEHIND ANALYSIS



**Testing**  
A few instances  
of arbitrary size



**Alloy: Bounded, exhaustive**  
All instances up to  
the given scope

- Logic in Alloy is undecidable
- Approach: Finite Model Finding
  - ▶ User provides a scope on each signature
  - ▶ Translation to a conjunctive normal form (CNF)
  - ▶ Off-the-shelf SAT solvers for instance generation

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## **MODELING IDIOMS IN ALLOY**

## ENCODING DYNAMIC BEHAVIORS

- Alloy has no built-in notion of states & operations
- Different idioms for encoding states in Alloy
  - ▶ A common idiom is to explicitly encode states as objects

```
sig State {  
    field : A -> B  
}  
pred op[s1, s2 : State] { ... }
```

## ANOTHER IDIOM: DYNAMIC (OR TIMED) RELATION

```
open util/ordering[Tick]
```

```
sig Tick {}
```

```
sig Component {  
  state : A -> B -> Tick  
}
```

```
pred step[t1, t2 : Tick, c : Component] { ... }
```

- Add Tick as the last column of mutable relations

## SOCIAL NETWORK EXAMPLE

```
sig Tick {}  
sig SocialNetwork {  
  friends : User -> User -> Tick  
  posts : User -> Post -> Tick  
}  
pred addPost[t1, t2 : Tick, n : SocialNetwork, u : User, p : Post] {  
  // post condition  
  n.posts.t1 = n.posts.t2 + u -> p  
  // frame condition  
  n.friends.t1 = n.friends.t2  
}
```

## TRACES IN ALLOY

```
fact Traces {  
  all t1 : Tick - last | let t2 = t1.next |  
    all n : SocialNetwork |  
      some u : User, p : Post |  
        addPost[t1, t2, n, u, p] or  
        removePost[t1, t2, n, u, p]  
}  
  
run {} for 3 but 5 Tick
```

## DYNAMIC RELATION IDIOM: BENEFITS & LIMITATIONS

- (+) Clear separation of static and dynamic parts of the state
- (+) Ability to generate traces and specify temporal assertions
- (-) Limited analysis support (liveness, fairness); bounded
- (-) Can be cumbersome to write

Can we overcome these limitations? Next session: Electrum!

## EXERCISES

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<https://github.com/haslab/Electrum2/wiki/Social-Network>

(exercises 3-4)